

TILT STABILITY, UNIFORM QUADRATIC GROWTH, AND STRONG METRIC REGULARITY OF THE SUBDIFFERENTIAL.

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Abstract. We prove that uniform second order growth, tilt stability, and strong metric regularity of the subdifferential — three notions that have appeared in entirely different settings — are all essentially equivalent for any lower-semicontinuous, extended-real-valued function.

Key words. Tilt stability, variational analysis, subdifferentials, quadratic growth, strong metric regularity, prox-regularity

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1. Introduction. Second-order conditions are ubiquitous in nonlinear optimization, in particular playing a central role in perturbation theory and in the analysis of algorithms. See for example [2, 16]. Classically, a point \bar{x} is called a *strong local minimizer* of a function f on \mathbf{R}^n if there exist $\kappa > 0$ and a neighbourhood U of \bar{x} such that the inequality

$$f(x) \geq f(\bar{x}) + \kappa|x - \bar{x}|^2 \quad \text{holds for all } x \in U.$$

Here $|\cdot|$ denotes the standard euclidean norm on \mathbf{R}^n . For smooth f , this condition simply amounts to positive definiteness of the Hessian $\nabla^2 f(\bar{x})$.

Existence of a strong local minimizer is a sufficient condition for a number of desirable properties: even in classical nonlinear programming, it typically drives local convergence analysis for algorithms. However, this notion has an important drawback, namely that strong local minimizers are sensitive to small perturbations to the function. To illustrate, the origin in \mathbf{R}^2 is a strong (global) minimizer of the convex function $f(x, y) = (|x| + |y|)^2$, whereas strong minimizers cease to exist for the slightly perturbed functions $f_t(x, y) = (|x| + |y|)^2 + t(x + y)$ for any $t \neq 0$.

In light of this instability, it is natural to look for a more robust quadratic growth condition, namely we would like the constant κ and the neighbourhood U , appearing in the definition of strong local minimizers, to be uniform relative to linear perturbations of the function.

DEFINITION 1.1 (Stable strong local minimizers). We will say that \bar{x} is a *stable strong local minimizer* of a function $f: \mathbf{R}^n \rightarrow \mathbf{R} \cup \{-\infty, +\infty\}$ if there is a constant $\kappa > 0$ and a neighbourhood U of \bar{x} so that for each vector v near the origin, there is a point x_v (necessarily unique) in U , with $x_0 = \bar{x}$, so that in terms of the perturbed functions $f_v := f(\cdot) - \langle v, x \rangle$, the inequality

$$f_v(x) \geq f_v(x_v) + \kappa|x - x_v|^2 \quad \text{holds for each } x \text{ in } U.$$

This condition appears under the name of uniform quadratic growth for tilt perturbations in [2], where it is considered in the context of optimization problems having a

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particular presentation. One could go further and require the dependence $v \mapsto x_v$ to be Lipschitz continuous, though it is easy to see that this requirement is automatically satisfied whenever \bar{x} is a stable strong local minimizer (see Proposition 2.2).

In the variational-analytic literature, conditioning and sensitivity of optimization problems is deeply tied to the notion of *metric regularity* [14, 5, 15, 8]. For us, the work of Artacho-Geoffroy [1] in this area will be particularly important. There the authors considered regularity properties of the workhorse of convex analysis, the convex subdifferential mapping $x \mapsto \partial f(x)$, and fully characterized such properties in terms of a variety of quadratic growth conditions. Results of the same flavour also appear in [2]. In this short note, we will generalize the equivalence [1, Corollary 3.9] to *all* lower-semicontinuous functions satisfying a natural continuity property. Consequently, we will show that for such a function f on \mathbf{R}^n and a local minimizer \bar{x} of f , the *limiting subdifferential* ∂f is *strongly metrically regular* at $(\bar{x}, 0)$ if and only if f is *prox-regular* at \bar{x} for 0 (see Definition 2.10) and \bar{x} is a stable strong local minimizer of f . We should note for the special case of *amenable functions*, this result has been proven in [2, Theorem 5.36]. In contrast, our approach is more intrinsic since it does not rely on the function representation.

Our proof strategy is straightforward. We will try to reduce the general situation to the convex case, thereby allowing us to apply [1, Corollary 3.9]. The key step in this direction is to observe that stable strong local minimizers are *tilt-stable*, in the sense of [13]. In fact, employing a reduction to the convex case, we will establish the surprising equivalence: stable strong local minimizers are one and the same as tilt-stable local minimizers (Corollary 3.2). We should also note that our results generalize [7, Theorem 6.3], which is only applicable to \mathbf{C}^2 -*partly smooth* functions satisfying a certain nondegeneracy condition.

As a by-product of our work, we will deduce that there is a complete characterization of stable strong local minimizers using positive definiteness of Mordukhovich's generalized Hessian $\partial^2 f(\bar{x}|0)$. For more details on the theory of generalized Hessians see [8, 9]. This is significant since there is now a fairly effective calculus of this second-order nonsmooth object [10], thereby providing the means of identifying stable strong local minimizers in many instances of practical importance.

2. Preliminaries. In this section, we summarize some of the fundamental tools used in variational analysis and nonsmooth optimization. We refer the reader to the monographs Borwein-Zhu [3], Clarke-Ledyev-Stern-Wolenski [4], Mordukhovich [8, 9], and Rockafellar-Wets [15], for more details. Unless otherwise stated, we follow the terminology and notation of [15].

The functions that we will be considering will take their values in the extended real line $\overline{\mathbf{R}} := \mathbf{R} \cup \{-\infty, \infty\}$. For a function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$, the *domain* of f is

$$\text{dom } f := \{x \in \mathbf{R}^n : f(x) < +\infty\},$$

and the *epigraph* of f is

$$\text{epi } f := \{(x, r) \in \mathbf{R}^n \times \mathbf{R} : r \geq f(x)\}.$$

We say that an extended-real-valued function is *proper* if it is never $\{-\infty\}$ and is not always $\{+\infty\}$. A function f is *lower-semicontinuous* (or *lsc* for short) at \bar{x} if the inequality $\liminf_{x \rightarrow \bar{x}} f(x) \geq f(\bar{x})$ holds.

Throughout this work, we will only use Euclidean norms. Hence for a point $x \in \mathbf{R}^n$, the symbol $|x|$ will denote the standard Euclidean norm of x . We let $\mathbf{B}_\epsilon(\bar{x})$ be an open ball around \bar{x} of radius ϵ , and we let $\overline{\mathbf{B}}_\epsilon(\bar{x})$ denote its closure.

2.1. Tilt stability. In establishing our main result, it will be crucial to relate the notion of stable strong local minimizers to the theory of tilt stability, introduced in [13]. We begin with a definition [13, Definition 1.1].

DEFINITION 2.1 (Tilt stability). A point \bar{x} gives a *tilt-stable local minimum* of the function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ if $f(\bar{x})$ is finite and there exists an $\epsilon > 0$ such that the mapping

$$M: v \mapsto \operatorname{argmin}_{|x-\bar{x}| \leq \epsilon} \{f(x) - \langle v, x \rangle\},$$

is single-valued and Lipschitz on some neighbourhood of 0 with $M(0) = \bar{x}$.

For \mathbf{C}^2 smooth functions, tilt stability reduces to positive-definiteness of the Hessian $\nabla^2 f(\bar{x})$ [13, Proposition 1.2]. We will see (Corollary 3.2) that the notions of tilt stability and stable strong local minimality are the same for *all* lsc functions — a rather surprising result. As a first step in establishing this equivalence, we now show that stable strong local minimizers depend in a Lipschitz way on the perturbation parameters.

PROPOSITION 2.2 (Lipschitzness of stable strong local minimizers).

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ and suppose that \bar{x} is a stable strong local minimizer of f . Then the correspondence $v \mapsto x_v$ of Definition 1.1 is locally Lipschitz around 0.

Proof. There is a constant κ so that for any vectors v, w near zero, we have

$$\begin{aligned} f(x_w) &\geq f(x_v) + \langle v, x_w - x_v \rangle + \kappa|x_v - x_w|^2, \\ f(x_v) &\geq f(x_w) + \langle w, x_v - x_w \rangle + \kappa|x_v - x_w|^2. \end{aligned}$$

Adding the two inequalities and dividing by $|x_v - x_w|^2$, we obtain

$$\left\langle \frac{v-w}{|x_v-x_w|}, \frac{x_v-x_w}{|x_v-x_w|} \right\rangle \geq 2\kappa.$$

We deduce $|x_v - x_w| \leq \frac{1}{2\kappa}|v - w|$, thereby establishing the result. \square

The following is now immediate.

PROPOSITION 2.3 (Stable strong local minimizers are tilt-stable).

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ and a point $\bar{x} \in \mathbf{R}^n$. If \bar{x} is a stable strong local minimizer of f , then \bar{x} gives a *tilt-stable local minimum* of f .

Proof. This readily follows from definition of tilt stability and Proposition 2.2. \square

The converse of the proposition above will take some more effort to prove. We will take this up in Section 3.

2.2. Some convex analysis. For any set $Q \subset \mathbf{R}^n$, the symbol $\operatorname{co} Q$ will denote the convex hull of Q , while $\overline{\operatorname{co}} Q$ will denote the closed convex hull of Q . Consider any function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ that is minorized by some affine function on \mathbf{R}^n . Then the set $\overline{\operatorname{co}}(\operatorname{epi} f)$ is an epigraph of a lsc, convex function, which we denote by $\overline{\operatorname{co}} f$. In some cases $\operatorname{co}(\operatorname{epi} f)$ is itself a closed set, and in such an instance, we refer to $\overline{\operatorname{co}} f$ simply as $\operatorname{co} f$. Observe that the inequality $\overline{\operatorname{co}} f \leq f$ always holds. For a set $S \subset \mathbf{R}^n$, we define the indicator function of S , denoted by δ_S , to be identically zero on S and $+\infty$ elsewhere.

For any (not necessarily convex) function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$, the *convex subdifferential* of f at \bar{x} , denoted by $\partial_{\operatorname{co}} f(\bar{x})$, consists of all vectors v satisfying

$$f(x) \geq f(\bar{x}) + \langle v, x - \bar{x} \rangle \text{ for all } x \in \mathbf{R}^n.$$

Equivalently, a vector v lies in $\partial_{\text{co}}f(\bar{x})$ if and only if \bar{x} is a global minimizer of the tilted function $x \mapsto f(x) - \langle v, x \rangle$. It will be important for us to understand the relationship between the convex subdifferential of a function f and the convex subdifferential of its convexification $\overline{\text{co}}f$. The following result will be especially important.

LEMMA 2.4. [6, Proposition 1.4.3 in Chapter X]

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ that is minorized by some affine function on \mathbf{R}^n . Then the implication

$$\partial_{\text{co}}f(x) \neq \emptyset \implies (\overline{\text{co}}f)(x) = f(x),$$

holds for any point x in \mathbf{R}^n .

The following lemma shows that under reasonable conditions, the set of minimizers of the convexified function $\overline{\text{co}}f$ coincides with the closed convex hull of minimizers of f . See [6, Remark 1.5.7, Lemma 1.5.3 in Chapter X] for more details.

LEMMA 2.5 (Minimizers of a convexified function).

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ with bounded domain, and suppose furthermore that f is minorized by some affine function on \mathbf{R}^n . Then $\text{co}(\text{epi } f)$ is a closed set, and we have

$$\underset{x \in \mathbf{R}^n}{\text{argmin}} (\text{co } f)(x) = \text{co} \left(\underset{x \in \mathbf{R}^n}{\text{argmin}} f(x) \right). \quad (2.1)$$

As a direct consequence, we obtain the important observation that tilt-stable minimizers are preserved under ‘‘local’’ convexification.

PROPOSITION 2.6 (Tilt-stable minimizers under convexification).

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ and suppose that a point $\bar{x} \in \mathbf{R}^n$ gives a tilt-stable local minimum f . Then for all sufficiently small $\epsilon > 0$, in terms of the function $g := f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})}$, we have

$$\underset{|x-\bar{x}| \leq \epsilon}{\text{argmin}} \{f(x) - \langle v, x \rangle\} = \underset{x \in \mathbf{R}^n}{\text{argmin}} \{(\text{co } g)(x) - \langle v, x \rangle\},$$

for all v sufficiently close to 0. Consequently \bar{x} gives a tilt-stable local minimum of the convexified function $\text{co}(f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})})$.

Proof. By definition of tilt stability, we have that $f(\bar{x})$ is finite, and for all sufficiently small $\epsilon > 0$, the mapping

$$M: v \mapsto \underset{|x-\bar{x}| \leq \epsilon}{\text{argmin}} \{f(x) - \langle v, x \rangle\},$$

is single-valued and Lipschitz on some neighbourhood of 0 with $M(0) = \bar{x}$. Letting $g := f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})}$ and applying Lemma 2.5 to the function $x \mapsto g(x) - \langle v, x \rangle$, we deduce

$$\begin{aligned} M(v) &= \underset{x \in \mathbf{R}^n}{\text{argmin}} \{g(x) - \langle v, x \rangle\} = \text{co} \left(\underset{x \in \mathbf{R}^n}{\text{argmin}} \{g(x) - \langle v, x \rangle\} \right) = \\ &= \underset{x \in \mathbf{R}^n}{\text{argmin}} \{ \text{co}(g(\cdot) - \langle v, \cdot \rangle)(x) \} = \underset{x \in \mathbf{R}^n}{\text{argmin}} \{ (\text{co } g)(x) - \langle v, x \rangle \}, \end{aligned}$$

for all v sufficiently close to 0. The result follows. \square

2.3. Variational analysis preliminaries. A set-valued mapping F from \mathbf{R}^n to \mathbf{R}^m , denoted by $F: \mathbf{R}^n \rightrightarrows \mathbf{R}^m$, is a mapping from \mathbf{R}^n to the power set of \mathbf{R}^m . Thus for each point $x \in \mathbf{R}^n$, $F(x)$ is a subset of \mathbf{R}^m . The graph of F is defined to be

$$\text{gph } F := \{(x, y) \in \mathbf{R}^n \times \mathbf{R}^m : y \in F(x)\}.$$

A mapping $F: \mathbf{R}^n \rightrightarrows \mathbf{R}^n$ is called *monotone* provided that

$$\langle v_1 - v_0, x_1 - x_0 \rangle \geq 0 \text{ whenever } v_0 \in F(x_0), v_1 \in F(x_1).$$

It is *maximal monotone* if there is no other monotone mapping whose graph strictly contains the graph of F . In particular, the convex subdifferential mapping $\partial_{co}f$ of a proper, lsc convex function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ is maximal monotone [15, Theorem 12.17].

A set-valued mapping $F: \mathbf{R}^n \rightrightarrows \mathbf{R}^n$ is *strongly monotone* if there exists $\sigma > 0$ such that the mapping $F - \sigma I$ is monotone, or equivalently

$$\langle v_1 - v_0, x_1 - x_0 \rangle \geq \sigma |x - \bar{x}|^2 \text{ whenever } v_0 \in F(x_0), v_1 \in F(x_1).$$

If for a convex function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$, the subdifferential mapping $\partial_{co}f$ is strongly monotone, then we say that f is *strongly convex*.

Often we will be interested in restricting both the domain and the range of a set-valued mapping. Hence for a set-valued mapping $F: \mathbf{R}^n \rightrightarrows \mathbf{R}^m$, and neighbourhoods $U \subset \mathbf{R}^n$ and $V \subset \mathbf{R}^m$, we define the *localization of F relative to U and V* to simply be the set-valued mapping $\hat{F}: \mathbf{R}^n \rightrightarrows \mathbf{R}^m$ whose graph is $(U \times V) \cap \text{gph } F$.

A central notion in set-valued and variational analysis that we explore in this work is strong metric regularity.

DEFINITION 2.7 (Strong metric regularity). A mapping $F: \mathbf{R}^n \rightrightarrows \mathbf{R}^m$ is said to be *strongly metrically regular* at \bar{x} for \bar{v} , where $\bar{v} \in F(\bar{x})$, if there exist neighbourhoods U of \bar{x} and V of \bar{v} so that the localization of F^{-1} relative to V and U defines a (single-valued) Lipschitz continuous mapping.

This condition plays a central role in stability theory since it guarantees that near \bar{x} , there is a unique solution for v near \bar{v} of the inclusion

$$v \in F(x),$$

which furthermore varies in a Lipschitz way relative to perturbations in the left-hand-side. For other notions related to metric regularity, we refer the interested reader to the recent monograph [14].

In the current work, we will use, and subsequently generalize beyond convexity, the following result that has appeared as [1, Theorem 3.9].

THEOREM 2.8 (Strong metric regularity of the convex subdifferential).

Consider a lsc convex function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ and a point \bar{x} in \mathbf{R}^n . Then the following are equivalent

1. $\partial_{co}f$ is strongly metrically regular at $(\bar{x}, 0)$.
2. There exists $\kappa > 0$ and neighbourhoods U of \bar{x} and V of 0 so that the localization of $(\partial_{co}f)^{-1}$ relative to V and U is single-valued and we have

$$f(x) \geq f(\bar{x}) + \langle \bar{v}, x - \bar{x} \rangle + \kappa |x - \bar{x}|^2 \quad \text{for all } x \in U,$$

and all $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial_{co}f$.

Clearly, for convex functions, property 2 in the theorem above is equivalent to \bar{x} being a stable strong local minimizer of f .

We now consider subdifferentials, which are the fundamental tools in the study of general nonsmooth functions.

DEFINITION 2.9 (Subdifferentials). Consider a function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ and a point \bar{x} with $f(\bar{x})$ finite. The *proximal subdifferential* of f at \bar{x} , denoted by $\partial_P f(\bar{x})$, consists of all vectors $v \in \mathbf{R}^n$ for which there exists $r > 0$ satisfying

$$f(x) \geq f(\bar{x}) + \langle v, x - \bar{x} \rangle - r |x - \bar{x}|^2 \text{ for all } x \text{ near } \bar{x}.$$

On the other hand, the *limiting subdifferential* of f at \bar{x} , denoted by $\partial f(\bar{x})$, consists of all vectors v for which there exists a sequence $(x_i, f(x_i), v_i) \rightarrow (\bar{x}, f(\bar{x}), \bar{v})$, with $v_i \in \partial_P f(x_i)$ for each index i .

For \mathbf{C}^1 smooth functions f on \mathbf{R}^n , the subdifferential $\partial f(x)$ consists only of the gradient $\nabla f(x)$ for each $x \in \mathbf{R}^n$. For convex f , the proximal and the limiting subdifferentials coincide with the convex subdifferential $\partial_{co} f(\bar{x})$.

Seeking a kind of uniformity in parameters appearing in the definition of the proximal subdifferential, we arrive at the following [12, Definition 1.1].

DEFINITION 2.10 (Prox-regularity). A function $f: \mathbf{R}^n \rightarrow \bar{\mathbf{R}}$ is prox-regular at \bar{x} for \bar{v} if f is finite and locally lsc at \bar{x} with $v \in \partial f(\bar{x})$, and there exist $\epsilon > 0$ and $\rho \geq 0$ such that

$$f(x') \geq f(x) + \langle v, x' - x \rangle - \frac{\rho}{2} |x' - x|^2 \text{ for all } x' \in \mathbf{B}_\epsilon(\bar{x}),$$

when $v \in \partial f(x)$, $|v - \bar{v}| < \epsilon$, $|x - \bar{x}| < \epsilon$, $|f(x) - f(\bar{x})| < \epsilon$.

In relating strong metric regularity of the subdifferential ∂f to the functional properties of f , it is absolutely essential to require the function $(x, v) \mapsto f(x)$ to be continuous on $\text{gph } \partial f$. This leads to the notion of subdifferential continuity, introduced in [12, Definition 2.1].

DEFINITION 2.11 (Subdifferential continuity). We say that $f: \mathbf{R}^n \rightarrow \bar{\mathbf{R}}$ is *subdifferentially continuous at \bar{x} for $\bar{v} \in \partial f(\bar{x})$* if for any sequences $x_i \rightarrow \bar{x}$ and $v_i \rightarrow \bar{v}$, with $v_i \in \partial f(x_i)$, it must be the case that $f(x_i) \rightarrow f(\bar{x})$.

In particular, all lsc convex functions f , and more generally all strongly amenable functions (see [15, Definition 10.23]), are both subdifferentially continuous and prox-regular at any point $\bar{x} \in \text{dom } f$ for any vector $\bar{v} \in \partial f(\bar{x})$. See [15, Proposition 13.32] for details.

Rockafellar and Poliquin characterized tilt stability in a number of meaningful ways [13, Theorem 1.3], with the notions of prox-regularity and subdifferential continuity playing a key role. The following is just a small excerpt from their result.

THEOREM 2.12 (Characterization of tilt stability). *Consider a function $f: \mathbf{R}^n \rightarrow \bar{\mathbf{R}}$, with $0 \in \partial f(\bar{x})$, and such that f is both prox-regular and subdifferentially continuous at \bar{x} for $\bar{v} = 0$. Then the following are equivalent and imply the existence of $\epsilon > 0$ such that the mapping M in Definition 2.1 has the equivalent form $M(v) = (\partial f)^{-1}(v) \cap \mathbf{B}_\epsilon(\bar{x})$ for all v sufficiently close to 0.*

1. *The point \bar{x} gives a tilt-stable local minimum of f .*
2. *There is a proper, lsc, strongly convex function h on \mathbf{R}^n along with neighbourhoods U of \bar{x} and V of 0 such that h is finite on U , with $h(\bar{x}) = f(\bar{x})$, and*

$$(U \times V) \cap \text{gph } \partial f = (U \times V) \cap \text{gph } \partial h.$$

Analysing the proof of the above theorem, much more can be said. Indeed, suppose that the set-up of the theorem holds and that \bar{x} gives a tilt-stable local minimum of f . Thus there exists $\epsilon > 0$ such that the mapping

$$M : v \mapsto \underset{|x - \bar{x}| \leq \epsilon}{\text{argmin}} \{f(x) - \langle v, x \rangle\},$$

is single-valued and Lipschitz continuous on some neighbourhood of 0 with $M(0) = \bar{x}$. Then the convex function h guaranteed to exist by Theorem 2.12 can be chosen simply to be the convexified function

$$h = \text{co} (f + \delta_{\bar{\mathbf{B}}_\epsilon(\bar{x})}).$$

This observation will be important for the proof of our main result Theorem 3.3.

3. Main results. We begin this section by establishing a simple relationship between tilt stability and strong metric regularity of the subdifferential ∂f .

PROPOSITION 3.1 (Tilt stability versus strong metric regularity).

Let $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ be a lsc function and let \bar{x} be a local minimizer of f . Consider the following properties.

1. The subdifferential mapping ∂f is strongly metrically regular at $(\bar{x}, 0)$.

2. f is prox-regular at \bar{x} for 0 and \bar{x} gives a tilt-stable local minimum of f .

Then the implication 1 \Rightarrow 2 holds, and furthermore if 1 holds, then for sufficiently small $\epsilon > 0$ the mapping M of Definition 2.1 has the representation

$$M(v) = \mathbf{B}_\epsilon(\bar{x}) \cap (\partial f)^{-1}(v),$$

for all v sufficiently close to 0. The implication 2 \Rightarrow 1 holds provided that f is subdifferentially continuous at \bar{x} for 0.

Proof. Suppose that 1 holds. Then, in particular, \bar{x} is a strict local minimizer of f . Hence there exists $\epsilon > 0$ satisfying

$$f(x) > f(\bar{x}) \text{ for all } x \in \overline{\mathbf{B}}_\epsilon(\bar{x}).$$

It is now easy to check that the sets $\operatorname{argmin}_{|x-\bar{x}| \leq \epsilon} \{f(x) - \langle v, x \rangle\}$ are contained in the open ball $\mathbf{B}_\epsilon(\bar{x})$ for all vectors v sufficiently close to 0. Hence by strong metric regularity we have

$$\mathbf{B}_\epsilon(\bar{x}) \cap (\partial f)^{-1}(v) = \operatorname{argmin}_{|x-\bar{x}| \leq \epsilon} \{f(x) - \langle v, x \rangle\},$$

for all v sufficiently close to 0. It follows from the equation above and the definition of prox-regularity that f is prox-regular at \bar{x} for 0. The validity of 2 is now immediate.

Suppose that f is subdifferentially continuous at \bar{x} for 0 and that 2 holds. Then by Theorem 2.12, we have $M(v) = \mathbf{B}_\epsilon(\bar{x}) \cap (\partial f)^{-1}(v)$, and consequently ∂f is strongly metrically regular at $(\bar{x}, 0)$. \square

We can now establish the converse of Proposition 2.3, thereby showing that tilt-stable local minimizers and stable strong local minimizers are one and the same.

COROLLARY 3.2 (Stable strong local minimizers and tilt stability).

For a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$, a point \bar{x} gives a tilt-stable local minimum of f if and only if \bar{x} is a stable strong local minimizer of f .

Proof. The implication \Leftarrow has been proven in Proposition 2.3. We now argue the converse. To this end, suppose that \bar{x} gives a tilt-stable local minimum of f . Then by Proposition 2.6, for all sufficiently small $\epsilon > 0$, the point \bar{x} gives a tilt-stable local minimum of the convexified function $\operatorname{co}(f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})})$, and furthermore, in terms of the function $g := f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})}$, we have

$$\operatorname{argmin}_{x \in \mathbf{R}^n} \{g(x) - \langle v, x \rangle\} = \operatorname{argmin}_{x \in \mathbf{R}^n} \{(\operatorname{co} g)(x) - \langle v, x \rangle\}, \quad (3.1)$$

for all v sufficiently close to 0. In light of (3.1), we have

$$v \in \partial_{\operatorname{co} g}(x) \Leftrightarrow v \in \partial_{\operatorname{co}}(\operatorname{co} g)(x), \quad (3.2)$$

for all $x \in \mathbf{R}^n$ and all v sufficiently close to 0.

Observe $\operatorname{co} g$, being a lsc convex function, is both prox-regular and subdifferentially continuous at \bar{x} for 0. Hence applying Proposition 3.1 to $\operatorname{co} g$, we deduce that

the subdifferential $\partial_{co}(\text{co } g)$ is strongly metrically regular at $(\bar{x}, 0)$. Consequently by Theorem 2.8, there exists $\kappa > 0$ and neighbourhoods U of \bar{x} and V of 0 so that the localization of $(\partial_{co}(\text{co } g))^{-1}$ relative to V and U is single-valued and we have

$$(\text{co } g)(x) \geq (\text{co } g)(\tilde{x}) + \langle \tilde{v}, x - \tilde{x} \rangle + \kappa|x - \tilde{x}|^2 \quad \text{for all } x \in U, \quad (3.3)$$

and for all $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial_{co}(\text{co } g)$.

Shrinking U and V , we may assume that the inclusion $U \subset \mathbf{B}_\epsilon(\bar{x})$ holds. Combining (3.2) and Lemma 2.4, we deduce that for any pair $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial_{co}(\text{co } g)$, we have $(\text{co } g)(\tilde{x}) = g(\tilde{x}) = f(\tilde{x})$, and that for any $x \in U$ the inequality $(\text{co } g)(x) \leq f(x)$ holds. Plugging these relations into (3.3), the result follows. \square

With the preparation that we have done, the proof of our main result is now straightforward. We should stress that our contribution is in the proof of the equivalence $1 \Leftrightarrow 2 \Leftrightarrow 3 \Leftrightarrow 4$, whereas the equivalence $2 \Leftrightarrow 5$ follows directly from [12, Theorem 3.2] and [13, Theorem 1.3].

THEOREM 3.3 (Strong metric regularity and quadratic growth).

Consider a lsc function $f: \mathbf{R}^n \rightarrow \overline{\mathbf{R}}$ that is subdifferentially continuous at \bar{x} for 0, where \bar{x} is a local minimizer of f . Then the following are equivalent.

1. The subdifferential mapping ∂f is strongly metrically regular at $(\bar{x}, 0)$.
2. f is prox-regular at \bar{x} for 0 and \bar{x} gives a tilt-stable local minimum of f .
3. There exists $\kappa > 0$ and neighbourhoods U of \bar{x} and V of 0 so that the localization of $(\partial f)^{-1}$ relative to V and U is single-valued and we have

$$f(x) \geq f(\tilde{x}) + \langle \tilde{v}, x - \tilde{x} \rangle + \kappa|x - \tilde{x}|^2 \quad \text{for all } x \in U,$$

and for all $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial f$.

4. f is prox-regular at \bar{x} for 0 and \bar{x} is a stable strong local minimizer of f
5. ∂f has a localization around $(\bar{x}, 0)$ that is strongly monotone and maximal monotone.

Proof. The equivalence $1 \Leftrightarrow 2$ was proven in Proposition 3.1, whereas the equivalence $2 \Leftrightarrow 5$ follows directly from [12, Theorem 3.2] and [13, Theorem 1.3].

$2 \Rightarrow 3$: Suppose 2 holds. Then by Theorem 2.12 and the ensuing remarks, there is $\epsilon > 0$ so that for the convexified function $h := \text{co}(f + \delta_{\overline{\mathbf{B}}_\epsilon(\bar{x})})$, we have

$$\text{gph } \partial f = \text{gph } \partial h \text{ locally around } (\bar{x}, 0).$$

From Proposition 2.6 and the equivalence $1 \Leftrightarrow 2$, we deduce that the mapping ∂h is strongly metrically regular at $(\bar{x}, 0)$. Applying Theorem 2.8 to h , we deduce there exists $\kappa > 0$ and neighbourhoods U of \bar{x} and V of 0 so that the localization of $(\partial f)^{-1}$ relative to V and U is single-valued and we have

$$h(x) \geq h(\tilde{x}) + \langle \tilde{v}, x - \tilde{x} \rangle + \kappa|x - \tilde{x}|^2 \quad \text{for all } x \in U, \quad (3.4)$$

and for all $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial f$. Shrinking U and V , we may assume that the inclusion $U \subset \mathbf{B}_\epsilon(\bar{x})$ holds. Observe by Proposition 3.1, we have

$$\underset{|x - \bar{x}| \leq \epsilon}{\text{argmin}} \{f(x) - \langle \tilde{v}, x \rangle\} = \mathbf{B}_\epsilon(\bar{x}) \cap (\partial f)^{-1}(\tilde{v}),$$

for all \tilde{v} sufficiently close to 0. In particular, we may shrink V so that for all pairs $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial f$, we have $\partial_{co} f(\tilde{x}) \neq \emptyset$. Then applying Lemma 2.4, we deduce $h(\tilde{x}) = f(\tilde{x})$ for all $(\tilde{x}, \tilde{v}) \in (U \times V) \cap \text{gph } \partial f$, and $h(x) \leq f(x)$ for all $x \in U$. Plugging these relations into (3.4), the result follows immediately.

3 \Rightarrow 4: This follows directly from the definitions of prox-regularity and stable strong local minimizers.

4 \Rightarrow 2: This implication is immediate from Proposition 2.3. \square

As the above theorem illustrates, prox-regularity appears naturally when characterizing strong metric regularity of the subdifferential, thereby underscoring the importance of the concept. This is in contrast to [13, Theorem 1.3] where prox-regularity occurs as a standing assumption. Furthermore the following example shows that tilt stability does not necessarily imply that prox-regularity holds, even for Lipschitz continuous, *subdifferentially regular* [15, Corollary 8.11] functions. Hence the assumption of prox-regularity in conditions 2 and 4 of Theorem 3.3 is not superfluous.

EXAMPLE 3.4 (Failure of prox-regularity). Consider the Lipschitz continuous function

$$f(x) = \begin{cases} \min \left\{ \left(1 + \frac{1}{n}\right)x - \frac{1}{n(n+1)}, \frac{1}{n} \right\}, & \frac{1}{n+1} \leq |x| \leq \frac{1}{n} \\ 0, & x = 0 \end{cases}$$

Clearly $\bar{x} = 0$ gives a tilt-stable local minimum of f . Observe however

$$(\partial f)^{-1}(0) \supset \left\{ \frac{1}{n} : n \text{ is a nonzero integer} \right\},$$

and hence the subdifferential mapping ∂f is not strongly metrically regular at $(0, 0)$. Of course this situation occurs because f is not prox-regular at \bar{x} for 0.

To make this example more convincing, it is easy to “smooth-out” f on the open sets $\{x : \frac{1}{n+1} < |x| < \frac{1}{n}\}$, to ensure that f is subdifferentially regular on the whole real line. For instance, let

$$r_n = \frac{1}{(n+1)^3} + \frac{1}{(n+1)^2} \sqrt{\left(\frac{1}{n}\right)^2 + \left(\frac{1}{n+1}\right)^2}, \quad (3.5)$$

$$x_n = \frac{1}{n} + \frac{1}{(n+1)^4} \left(1 - n(n+1)(n+2)r_n\right). \quad (3.6)$$

and define the function

$$\tilde{f}(x) = \begin{cases} \left\{ \begin{array}{ll} \left(1 + \frac{1}{n}\right)x - \frac{1}{n(n+1)}, & \frac{1}{n+1} \leq |x| \leq x_n \\ \sqrt{r_n^2 - \left(x - \frac{1}{n}\right)^2} - \left(r_n - \frac{1}{n}\right), & x_n \leq |x| \leq \frac{1}{n} \end{array} \right. \\ 0, & x = 0 \end{cases}$$

The construction is depicted in Figure 3.1.

One can readily verify that \tilde{f} is indeed subdifferentially regular on the entire real line, and for the same reasons as for f , the subdifferential mapping $\partial \tilde{f}$ is not strongly metrically regular at $(0, 0)$ even though $(0, 0)$ gives a tilt-stable local minimum of \tilde{f} . This happens because \tilde{f} is not prox-regular at \bar{x} for 0.

It is important to note that subdifferential continuity plays an important role in the validity of Theorem 3.3, as the following example shows.

EXAMPLE 3.5 (Failure of subdifferential continuity). Consider the function f on \mathbf{R} defined by

$$f(x) = \begin{cases} 1 + x^4, & x < 0, \\ x^2, & x \geq 0. \end{cases}$$

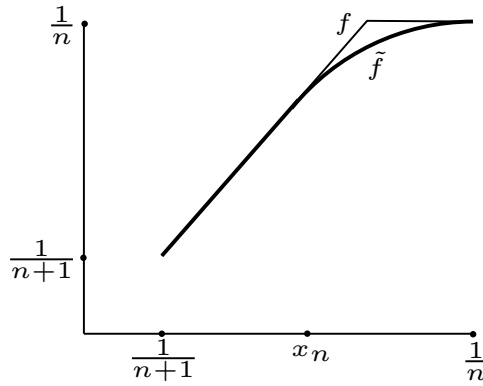


FIG. 3.1. Graphs of f and \tilde{f} on the interval $(\frac{1}{n+1}, \frac{1}{n})$.

One can easily check that f is prox-regular at $\bar{x} = 0$ for $\bar{v} = 0$ and that the origin is a stable strong local minimizer of f . However ∂f fails to be strongly metrically regular at $(0, 0)$. This occurs, of course, because f is not subdifferentially continuous at $\bar{x} = 0$ for $\bar{v} = 0$.

REMARK 3.6. In light of [13, Theorem 1.3], we may add another equivalence to Theorem 3.3, namely that f is prox-regular at \bar{x} for 0 and the generalized Hessian mapping $\partial^2 f(\bar{x}|0)$ is positive definite in the sense that

$$\langle z, w \rangle > 0 \text{ whenever } z \in \partial^2 f(\bar{x}|0)(w), \ w \neq 0. \quad (3.7)$$

Hence in concrete instances, we may use the newly developed calculus of the generalized Hessians [10] and the calculus of prox-regularity [11] to determine when any of the equivalent properties listed in Theorem 3.3 hold. It is also worth noting that such calculations are drastically simplified when f is convex. In this situation, by [14, Theorem 3G.5] and [15, Theorem 9.43] for example, strong metric regularity of ∂f at $(\bar{x}, 0)$ amounts to nonsingularity of the generalized Hessian

$$0 \in \partial^2 f(\bar{x}|0)(w) \implies w = 0,$$

a condition that is much easier to check in practice than the positive definiteness condition (3.7).

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