

# A note on Legendre-Fenchel conjugate of the product of two positive-definite quadratic forms

Yong Xia

Received: date / Accepted: date

**Abstract** The Legendre-Fenchel conjugate of the product of two positive-definite quadratic forms was posted as an open question in the field of nonlinear analysis and optimization by Hiriart-Urruty [‘Question 11’ in *SIAM Review* 49, 255-273, (2007)]. Under a convex assumption on the function, it was answered by Zhao [SIAM J. Matrix Analysis & Applications, 31(4), 1792-1811 (2010)]. In this note, we answer the open question without making the convexity assumption.

**Keywords** Legendre-Fenchel conjugate · quadratic form

**PACS** 15A48 · 65F15 · 65K05 · 90C25

## 1 Introduction

The Legendre-Fenchel conjugate of the function  $h(y)$  is defined as

$$h^*(x) = \sup_{y \in R^n} x^T y - h(y).$$

For example, if  $h(y) = \frac{1}{2}y^T A y$ , where  $A$  is positive definite, then  $h^*(x) = \frac{1}{2}x^T A^{-1} x$ . In the field of nonlinear analysis and optimization, J.B. Hiriart-Urruty [1] raised an open question *what is the expression or formula of the conjugate of the product function*

$$f(y) = \frac{1}{4}(y^T A y)(y^T B y),$$

---

This research was supported by National Natural Science Foundation of China under grants 11001006 and 91130019/A011702, and by the fund of State Key Laboratory of Software Development Environment under grant SKLSDE-2011ZX-15.

Y. Xia

State Key Laboratory of Software Development Environment, LMIB of the Ministry of Education, School of Mathematics and System Sciences, Beihang University, Beijing 100191, P. R. China E-mail: dearyxia@gmail.com

where  $A, B$  are two  $n \times n$  positive definite matrices.

Recently, Zhao [3] answered the open question under the assumption that  $f(y)$  is convex. The main result is as follows.

**Theorem 1** ([3]) *Let the function  $f(y)$  be convex. At any point  $x \in R^n$ , the value of the conjugate  $f^*(x)$  is finite, and  $f^*(x) = 0$  if  $x = 0$ , otherwise if  $x \neq 0$ ,*

$$f^*(x) = p(\alpha) := 3\alpha^{1/3} \left( \frac{x^T(A + \alpha B)^{-1}x}{4} \right)^{2/3},$$

where  $\alpha$  is any real root of the univariate equation

$$g(\alpha) := \alpha - \frac{x^T(A + \alpha B)^{-1}A(A + \alpha B)^{-1}x}{x^T(A + \alpha B)^{-1}B(A + \alpha B)^{-1}x} = 0. \quad (1)$$

The following gives a sufficient condition under which the real root to the equation (1) is unique.

**Theorem 2** ([3]) *If  $\max\{\kappa(A), \kappa(B)\} \leq 2.5$ , where  $\kappa(\cdot)$  denotes the condition number, then  $f(y)$  is convex and for any  $x \neq 0$ , there exists a unique real root to the equation (1).*

In this note, we answer the open question without the convexity assumption. Our proof is much shorter than that of Theorem 1 given in [3]. As a corollary, the sufficient condition (Theorem 2) is improved.

## 2 Main Result

In this section, we study the conjugate  $f^*(x) = \sup_{y \in R^n} x^T y - f(y)$  without assuming that  $f(y)$  is convex.

**Lemma 1** *The conjugate  $f^*(x)$  is finite.  $f^*(x) = 0$  if  $x = 0$ , otherwise if  $x \neq 0$ ,  $f^*(x) > 0$ .*

Proof. The finiteness of  $f^*(x)$  follows from

$$\lim_{\|y\|_2 \rightarrow \infty} x^T y - \frac{1}{4}(y^T A y)(y^T B y) \leq \lim_{\|y\|_2 \rightarrow \infty} x^T y - \frac{\lambda_{\min}(A)\lambda_{\min}(B)}{4} \|y\|_2^4 = -\infty,$$

where  $\lambda_{\min}(A) > 0$  and  $\lambda_{\min}(B) > 0$  are the minimum eigenvalues of  $A$  and  $B$ , respectively. If  $x = 0$ , it is trivial to verify  $f^*(x) = 0$ . Now we assume  $x \neq 0$ . Since

$$\max_{\epsilon} \{x^T(\epsilon x) - f(\epsilon x)\} = \max_{\epsilon} \{x^T x \epsilon - (x^T A x)(x^T B x) \epsilon^2\} = \frac{(x^T x)^2}{(x^T A x)(x^T B x)} > 0,$$

we have  $f^*(x) > 0$ . The proof is complete.  $\square$

**Lemma 2** Suppose  $x \neq 0$ .  $y$  is a stationary point of  $x^T y - f(y)$  if and only if

$$x^T y - f(y) = p(\alpha),$$

where  $\alpha$  is a real root of the univariate equation (1).

Proof. Suppose  $y$  is a stationary point of  $x^T y - f(y)$ , we have

$$x = \nabla f(y) = \left( \frac{1}{2}(y^T A y)B + \frac{1}{2}(y^T B y)A \right) y.$$

The assumption  $x \neq 0$  implies that  $y \neq 0$ . Therefore,

$$y = 2(\beta B + \gamma A)^{-1} x, \quad (2)$$

where  $\beta = y^T A y > 0$  and  $\gamma = y^T B y > 0$ . Substituting (2) into  $y^T A y$  and  $y^T B y$ , we have

$$\beta = 4x^T (\beta B + \gamma A)^{-1} A (\beta B + \gamma A)^{-1} x, \quad (3)$$

$$\gamma = 4x^T (\beta B + \gamma A)^{-1} B (\beta B + \gamma A)^{-1} x. \quad (4)$$

Dividing (3) by (4) yields

$$\frac{\beta}{\gamma} - \frac{x^T (A + \frac{\beta}{\gamma} B)^{-1} A (A + \frac{\beta}{\gamma} B)^{-1} x}{x^T (A + \frac{\beta}{\gamma} B)^{-1} B (A + \frac{\beta}{\gamma} B)^{-1} x} = 0.$$

That is,  $\alpha := \frac{\beta}{\gamma}$  is a real root of (1). According to (3) and (4), we have

$$\begin{aligned} & x^T (A + \alpha B)^{-1} x \\ &= x^T (A + \alpha B)^{-1} A (A + \alpha B)^{-1} x + \alpha x^T (A + \alpha B)^{-1} B (A + \alpha B)^{-1} x \\ &= \frac{1}{4} \beta \gamma^2 + \frac{1}{4} \alpha \gamma^3 \\ &= \frac{1}{2} \alpha \gamma^3, \end{aligned}$$

which implies that

$$\gamma = \left( \frac{2x^T (A + \alpha B)^{-1} x}{\alpha} \right)^{1/3}. \quad (5)$$

Therefore, it follows from (2), (5) and the definitions of  $\beta$ ,  $\gamma$  and  $\alpha$  that

$$x^T y - f(y) = \frac{2}{\gamma} x^T (A + \alpha B)^{-1} x - \frac{1}{4} \beta \gamma = 3\alpha^{1/3} \left( \frac{x^T (A + \alpha B)^{-1} x}{4} \right)^{2/3}.$$

On the other hand, let  $\alpha$  be a real root of (1). Define  $\gamma$  as in (5). Let  $\beta = \alpha \gamma$ . Define  $y$  as in (2). Then  $y$  is a stationary point. The proof is complete.  $\square$

**Lemma 3** Suppose  $x \neq 0$ .  $x^T y - f(y)$  has at most  $2n - 1$  stationary points, which can be solved to any given precision in polynomial time.

Proof. According to Lemma 2, the number of stationary points of  $x^T y - f(y)$  is equal to the number of the real roots of Equation (1). Since  $A, B$  are positive definite, there exists a nonsingular matrix  $P$  such that both  $P^T AP$  and  $P^T BP$  are diagonal matrices. Assume  $P^T AP = \text{Diag}(a_1, \dots, a_n)$  and  $P^T BP = \text{Diag}(b_1, \dots, b_n)$ . Then for  $i = 1, \dots, n$ ,  $a_i > 0$  and  $b_i > 0$ . Let  $z = P^T x$ . Since  $P$  is nonsingular and  $x \neq 0$ , we have  $z \neq 0$ . It is trivial to verify that each root of Equation (1) satisfies

$$\left( \prod_{i=1}^n (a_i + \alpha b_i)^2 \right) \left( \alpha \sum_{i=1}^n \frac{b_i z_i^2}{(a_i + \alpha b_i)^2} - \sum_{i=1}^n \frac{a_i z_i^2}{(a_i + \alpha b_i)^2} \right) = 0, \quad (6)$$

which is a univariate polynomial equation of degree  $(2n - 1)$ . Therefore, Equation (1) has at most  $2n - 1$  real roots, which can be solved to any given precision in polynomial time [2]. The proof is complete.  $\square$

Now we present our main result.

**Theorem 3** *At any point  $x \in R^n$ , the value of the conjugate  $f^*(x)$  is finite, and  $f^*(x) = 0$  if  $x = 0$ , otherwise if  $x \neq 0$ ,*

$$f^*(x) = p(\alpha^*),$$

where  $\alpha^*$  is the maximizer of  $p(\alpha)$ , solved in polynomial time.

Proof. Since the maximizer of  $x^T y - f(y)$  must be a stationary point, it follows from Lemmas 1 and 2 that  $f^*(x) = p(\alpha^*)$ , where  $\alpha^* = \arg \max_{g(\alpha)=0} p(\alpha)$ . It is not difficult to verify that the equations  $\frac{dp(\alpha)}{d\alpha} = 0$  and  $g(\alpha) = 0$  are equivalent. Therefore,  $\alpha^* = \arg \max p(\alpha)$ . Moreover,  $\alpha^*$  can be solved by enumerating all the roots of  $g(\alpha) = 0$ , which is done in polynomial time according to the proof of Lemma 3.  $\square$

As a corollary, we show that Theorem 2 is improved.

**Theorem 4** ([3]) *If  $f(y)$  is convex, then for any  $x \neq 0$ , there exists a unique real root to the equation (1).*

Proof. If  $f(y)$  is convex, a stationary point of  $x^T y - f(y)$  is also a maximizer. It follows from Lemma 2 and Theorem 3 that any stationary point of  $p(\alpha)$  is also a global maximizer. According to Lemma 3 and the equivalence between  $\frac{dp(\alpha)}{d\alpha} = 0$  and  $g(\alpha) = 0$ ,  $p(\alpha)$  has  $k (\leq 2n - 1)$  stationary points, denoted by  $\alpha_1 < \dots < \alpha_k$ . It is sufficient to show  $k = 1$ . Suppose this is not true, i.e.,  $k \geq 2$ . Since  $p(\alpha_1) = p(\alpha_2)$  are the maximum value of  $p(\alpha)$ , for any  $\alpha \in (\alpha_1, \alpha_2)$ , we have  $p(\alpha) < p(\alpha_1)$ . Then there is a local minimizer in  $(\alpha_1, \alpha_2)$ , which is a stationary point and can not be a maximizer. Now, we obtain a contradiction. The proof is complete.  $\square$

### 3 Conclusion

The Legendre-Fenchel conjugate of the product of two positive-definite quadratic forms was posted as an open question by Hiriart-Urruty [1]. Under a convex assumption on the function, it was answered by Zhao [3]. In this note, we give an answer to the open question without making the convexity assumption. Our proof is much shorter than that of [3]. Finally, we raise an open question what is the expression of the conjugate of

$$f(y) = \frac{1}{4}(y^T A y)(y^T B y) + \frac{1}{2}y^T C y,$$

where  $A, B, C$  are positive definite matrices.

### References

1. J.B. Hiriart-Urruty, Potpourri of conjectures and open questions in nonlinear analysis and optimization, SIAM Review, 49, 255-273, (2007)
2. M. Sagraloff, When Newton meets Descartes: A Simple and Fast Algorithm to Isolate the Real Roots of a Polynomial, in Proceedings of the 37th International Symposium on Symbolic and Algebraic Computation, 297-304, ACM New York, NY, USA, 2012
3. Y.B. Zhao, The Legendre-Fenchel conjugate of the product of two positive-definite quadratic forms, SIAM J. Matrix Analysis & Applications, 31(4), 1792-1811 (2010)