

# A new mixed integer linear programming formulation for one problem of exploration of online social networks

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**Abstract** Enormous global popularity of online social network sites has initiated numerous studies and methods investigating different aspects of their use, so some concepts from network-based studies in optimization theory can be used for research into online networks. In Gajić (2014) are given a several new mixed integer linear programming formulations for first and second problem of exploration of online social networks introduced in Stanimirović and Mišković (2013). This paper introduces a new mixed integer linear programming formulation for remaining (third) problem. Numerical experiments show the performance of a commercial exact solver when applied to the proposed model. The new model is also compared with a model proposed in the literature using instances from single source capacitated facility location problem and randomly generated instances. The obtained results indicate that the proposed formulation clearly outperforms the existing formulation. Moreover, new formulation has small number of decision variables, so it is capable to find, by exact solver, upper and lower bounds on large-scale problem instances. The paper also noted and tried to correct some wrong considerations presented in the previous work.

**Keywords** Mixed integer linear programming · Location problems · Social networks · Combinatorial optimization

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## 1 Introduction

In the modern era, social networking is gaining importance. Social networks are usually defined in the literature as structures made of actors (generally humans) linked by relations [4]. For example, these relations may be phone calls or kinship. Consequently, the social networks are mostly represented as graphs, therefore social network optimization is closely related to graph optimization techniques. Therefore, some concepts from these techniques may be used for research of online networks.

Stanimirović and Mišković [2] were introduced a mixed integer linear programming (MILP) formulations for three problems (authors wrongly named them as models) for efficient analysis of an online social network. In order to solve these problems of larger dimensions, they also proposed three evolutionary metaheuristic approaches. As it can be reported in [1]: "Unfortunately, their paper is full of errors and deceptions. For example, all three evolutionary approaches were used crossover probabilities which were *larger than 1* (Stanimirović & Mišković, 2013, p. 241). Since the authors performed experiments on the problem instances that were generated randomly by themselves, and are unavailable to other researchers, the only valuable scientific content of that paper seems to be MILP formulations". Unfortunately, some errors in [2] were unnoticed previously:

- P. 236. The proof of Proposition 3.1 is incomplete (wrong), since it is proved only in one direction! Therefore, Algorithm 4 on p. 240, which describes objective function for Problem 3 in all three metaheuristic approaches, is not mathematically correct, although it work correctly;
- P. 237. Algorithm 2 which describes objective function for Problem 1 could not work correctly in case of ties between costs, i.e. cost from one user node to two or more potential control devices can be equal;
- P. 238. Algorithm 3 which describes objective function for Problem 2 also could not work correctly in case of ties between costs;
- P. 241. state "However, in the hybrid EA-LS and EA-TS methods, the crossover rate parameter is *decreased ...*", while it is obvious that it is increased;
- P. 250. "... showed that the CPLEX 12.1 solver provided optimal solutions only for small problem instances with up to 100 user nodes, while larger instances were out of its reach of CPLEX." As it can be seen from definition, problem hardness obviously grows linearly with number of user nodes  $m$ . Therefore, each method could routinely solve to optimality instances with small number of potential locations  $n$  and large number of user nodes  $m$ . Contrary, instances with small  $m$  and large  $n$  are very hard!
- P. 262. "The proposed mathematical models and hybrid metaheuristic methods may be used as additional tools for further research in this field". This sentence is only partially true, about models, but metaheuristic methods cannot be used at all, since they are wrongly and deceptively presented, with obvious false parameters (for example, crossover probability),

instances are unavailable to other researchers and even for small example has reported wrong optimal value.

Gajić [1] was proposed a several MILP formulations for first and second problem for efficient analysis of an online social network, incorporating several known closest assignment constraints from the literature. Experimental results contain the direct comparison between all formulations, performed on standard single source capacitated facility location problem instances. As it can be seen, the best formulation was based on *WF* closest assignment constraints proposed by Wagner and Falkson [3].

## 2 Existing mathematical formulation

In this section, Problem 3, that considers exploration of online social networks, is presented as it is defined in [2]. Let  $I = \{1, 2, \dots, m\}$  be the set of user nodes in the network, and  $J = \{1, 2, \dots, n\}$  a set of potential locations for establishing control devices. The non-negative matrix  $c_{ij} | i \in I, j \in J$  represents the cost of searching through the data from a user node  $i$  by a control device  $j$ . These costs may depend on the amount of time needed to explore one unit of data originating from  $i$  by device  $j$ , the distance and speed of Internet connection between them, etc. Exactly  $p$  potential locations must be established, and each user could be assigned to one or more open control devices in order to minimize the overall search process of online social network.

More precisely, in the Problem 3 (contrary from other two problems), a user node may split its out-coming data flow to several established control devices, i.e. user requirements can be (partially) served by some different established devices but out-coming flow of the considered user node must be equal to sum of these flow parts. The objective of the Problem 3 is to establish (exactly  $p$ ) control devices and to divide user requirements through open control devices in order to minimize the load balance of control devices.

The Problem 3 can be mathematically formulated in the following way. Let  $S \subset J$  denote the set of established control devices and  $x_{ij}$  is the fraction of information flow originating from a user node  $i$  and explored by a control device  $j$ . Then, objective function value  $obj(S) = \max_{i \in I, j \in S} c_{ij} \cdot x_{ij}$  subject to  $\sum_{j \in S} x_{ij} = 1$  for each  $i \in I$ . Note that for all  $j \notin S$  hold  $x_{ij} = 0$ . The optimal objective value of Problem 3 can be defined as  $opt_{P3} = \min_{S \subset J, |S|=p} obj(S)$ .

The mixed integer linear programming formulation of Problem 3 in [2] have the binary decision variables  $y_j, j = 1, \dots, n$ , real variables  $x_{ij}$  and real variable  $z$ . Using the previous notation, MILP was formulated as follows:

$$\min z \tag{1}$$

subject to:

$$\sum_{j \in J} y_j = p \quad (2)$$

$$x_{ij} \leq y_j, \quad \text{for all } i \in I, j \in J \quad (3)$$

$$\sum_{j \in J} x_{ij} = 1, \quad \text{for all } i \in I \quad (4)$$

$$c_{ij} \cdot x_{ij} \leq z, \quad \text{for all } i \in I, j \in J \quad (5)$$

$$x_{ij} \in [0, 1], y_j \in \{0, 1\}, z \geq 0 \quad \text{for all } i \in I, j \in J \quad (6)$$

The objective function (1) minimizes the load among control devices. Constraint (2) indicates that exactly  $p$  resource nodes are established. By constraints (3) and (4) it is ensured that each user node is assigned to exactly one established resource node. Constraints (5) impose lower bounds on the value of objective value  $z$ , while (6) reflect the nature of decision variables  $x_{ij}, y_j$  and  $z$ .

## 2.1 Illustrative example

*Example 1* [2] Let us consider a small network with  $m = 10$  user nodes and  $n = 6$  potential locations for establishing control devices. Suppose that exactly  $p = 3$  control devices are to be established with cost matrix

$$C = \begin{bmatrix} 10163 & 14 & 73 & 489 & 14588 & 125 \\ 113 & 234 & 29 & 12365 & 12657 & 265 \\ 12050 & 12955 & 132 & 73 & 368 & 0 \\ 12114 & 12765 & 114 & 221 & 42 & 143 \\ 192 & 14245 & 122 & 13123 & 169 & 33 \\ 10533 & 12446 & 195 & 294 & 325 & 133 \\ 25 & 171 & 393 & 385 & 11333 & 10765 \\ 370 & 14645 & 116 & 292 & 14748 & 449 \\ 286 & 13273 & 245 & 14095 & 497 & 82 \\ 476 & 11263 & 187 & 124 & 14359 & 275 \end{bmatrix}$$

Optimal objective function value of Problem 3, on this example, is equal to 90.213645, with established control devices 1, 3 and 6. Note that, in [2] is erroneously presented optimal solution for this problem as 90.124 with correct set of established control devices.  $\square$

### 3 An improved mathematical formulation

This section presents new mixed integer linear programming model for Problem 3. The binary decision variables  $y_j, j = 1, \dots, n$  have the same meaning as previous, and it can be introduced one continuous decision variable  $v$ , which define objective function. Using the previous notation, MILP was formulated as follows:

$$\max v \quad (7)$$

subject to (2) and

$$\sum_{j \in J} \frac{1}{c_{ij}} \cdot y_j \geq v, \quad \text{for all } i \in I \quad (8)$$

$$y_j \in \{0, 1\}, v \geq 0 \quad \text{for all } j \in J \quad (9)$$

The optimal objective value of Problem 3 is defined as  $opt_{P3} = \frac{1}{obj_{MILP}(y,v)}$ , while  $obj_{MILP}(y,v)$  is optimal objective function (7) subject to constraints (2), (8) and (9). New formulation have only  $n$  binary and 1 continuous decision variables, instead of  $n$  binary and  $m \cdot n + 1$  continuous decision variables in *MS* model. Therefore, new MILP formulation have much smaller number of decision variables than previous one, so it can be useful even for large-scale problem instances.

### 4 Experimental results

In this section, the computational results of proposed methods and their comparison with existing methods are presented. All experiments were carried out on an Intel Core i5-4670K, 3.4 GHz with 4 GB RAM memory under Windows 7 Professional operating system. In order to compare efficiency of proposed MILP formulations, CPLEX 12.5.1 solver is used.

Computational experiments were first performed, as in [1], on a Single Source Capacitated Plant Location Problem (SSCPLP) instances <http://www-eio.upc.es/~elena/sscplp/index.html> from  $m = 20, n = 10$  up to  $m = 90, n = 30$  with  $p = 5$ . The results are presented in Table 1, with following meaning of columns:

- Instance name;
- Number of user nodes  $m$ ;
- Number of potential locations  $n$ ;
- Optimal solution (obtained using both formulations);
- Running time of CPLEX solver, in seconds, using the existing *SM* formulation ([2]);
- Running time of CPLEX solver, in seconds, using the new formulation.

**Table 1** Computational results on SSCFLP instances

<i>Inst.</i>	<i>m</i>	<i>n</i>	<i>Opt</i>	<i>CPLEX time (sec.)</i>	
				<i>SM MILP</i>	<i>New MILP</i>
p1	20	10	9.997334	0.109	0.031
p2	20	10	8.768857	0.093	0.031
p3	20	10	8.169854	0.109	0.015
p4	20	10	10.500010	0.109	0.031
p5	20	10	13.988354	0.078	0.015
p6	20	10	9.986428	0.078	0.031
p7	30	15	12.318358	0.437	0.031
p8	30	15	8.239675	0.531	0.031
p9	30	15	9.959379	0.484	0.062
p10	30	15	8.309355	0.468	0.031
p11	30	15	9.104891	0.468	0.078
p12	30	15	9.729202	0.531	0.016
p13	30	15	9.729202	0.500	0.031
p14	30	15	10.461617	0.656	0.031
p15	30	15	7.683923	0.437	0.031
p16	30	15	7.683923	0.453	0.031
p17	30	15	9.680279	0.453	0.031
p18	40	20	9.939958	1.390	0.031
p19	40	20	9.204059	2.390	0.109
p20	40	20	9.324935	2.343	0.109
p21	40	20	9.570781	1.734	0.109
p22	40	20	9.139309	1.437	0.109
p23	40	20	9.113619	1.953	0.078
p24	40	20	9.271229	2.000	0.093
p25	40	20	8.958497	1.875	0.093
p26	50	20	10.284310	2.937	0.110
p27	50	20	9.657404	2.656	0.109
p28	50	20	9.218116	2.890	0.094
p29	50	20	11.399892	2.406	0.109
p30	50	20	10.466699	2.625	0.109
p31	50	20	9.098856	1.812	0.093
p32	50	20	8.811455	2.687	0.031
p33	50	20	9.880332	3.875	0.140
p34	60	30	10.236057	27.062	0.797
p35	60	30	10.123260	33.562	0.718
p36	60	30	9.465466	35.953	0.906
p37	60	30	9.974811	30.953	0.515
p38	60	30	10.160453	34.453	0.281
p39	60	30	10.322895	45.953	0.734
p40	60	30	10.617991	32.156	0.234
p41	60	30	9.096601	22.718	0.234
p42	75	30	10.541099	63.296	0.671
p43	75	30	10.535353	52.234	0.343
p44	75	30	9.414132	42.718	0.234
p45	75	30	10.120970	46.187	0.328
p46	75	30	10.568349	45.718	1.296
p47	75	30	10.387008	53.313	0.531
p48	75	30	11.359161	51.656	0.500
p49	75	30	10.161895	32.312	0.641
p50	90	30	10.499843	62.188	1.188
p51	90	30	10.445646	78.078	0.375
p52	90	30	10.485818	70.078	1.015
p53	90	30	10.901124	73.421	1.078
p54	90	30	10.942992	96.093	2.281
p55	90	30	10.446344	74.125	0.750
p56	90	30	10.857364	60.594	0.813
p57	90	30	10.694566	53.296	0.312
<i>Sum</i>				1261.121	18.859

**Table 2** Computational results on randomly generated instances

<i>Inst.</i>	<i>m</i>	<i>n</i>	<i>p</i>	<i>Opt</i>	<i>SM MILP</i>		<i>New MILP</i>	
					<i>Sol</i>	<i>t (sec)</i>	<i>Sol</i>	<i>t (sec)</i>
ins01	15	5	3	8.886831	<i>opt</i>	0.015	<i>opt</i>	0.015
ins02	15	7	4	33.178690	<i>opt</i>	0.015	<i>opt</i>	0.015
ins03	25	10	5	2.562945	<i>opt</i>	0.062	<i>opt</i>	0.016
ins04	25	12	7	0.038890	<i>opt</i>	0.062	<i>opt</i>	0.031
ins05	50	20	15	0.014998	<i>opt</i>	0.187	<i>opt</i>	0.046
ins06	100	30	15	0.012646	<i>opt</i>	87.42	<i>opt</i>	0.610
ins07	200	50	20	0.009827	0.01	5285	<i>opt</i>	129.5
ins08	300	50	25	0.007676	0.0083	14357	<i>opt</i>	757.2

As it can be seen from Table 1, on SSCFLP instances new MILP formulation clearly outperform the *SM* one, since the running times on new formulation are about 2 orders of magnitude smaller than running times on *SM*.

In the paper [2] is performed experiments on the large-scale problem instances that were generated randomly. Unfortunately, these problem instances remained unavailable to the author of this article. Therefore, the author of this article is generated instances, on the same way as in [2], except the different random seed numbers. Generator of these instances is publicly available on link <https://docs.google.com/document/d/1INC7scPd0aTIZQzV97SDiGoRk7dKDsFXNZv6910TLLw/pub>. This set of instances contains 40 instances with up to  $m = 20000$  user nodes and up to  $n = 500$  potential locations (same as in [2]), and it can be used as benchmark in future computational experiments on the presented problem.

The results of CPLEX solver using both formulations are given in Table 2, on similar way as in Table 1. Since the CPLEX solver using the *SM* formulation usually obtain "Out of memory" status in the initialization phase, without obtaining any integer solution, data about this formulation is omitted for large random instances (ins09-ins40). Although these instances are large, and CPLEX on new formulation also stopped its work with "Out of memory" status, integer solution (upper bound) and lower bound are reported.

As it can be seen from experimental results on random instances, new MILP formulation again clearly outperform the existing one. Moreover, it uses relatively small number of decision variables, so exact solvers can produce upper and lower bound on very large dimensions.

## 5 Conclusions

This paper considers the problem of efficient exploration of online social networks and a new MILP model for the proposed problem is presented. A new model has small number of decision variables so its running time on each instance is about 2 orders of magnitude smaller than previous one, when obtaining optimal solution. Additionally, it can be used for obtaining upper and lower bounds of reasonable quality in solving large-scale instances. It is also noted some wrong sentences from the literature and tried to correct them.

**Table 3** Upper and lower bounds on large randomly generated instances

<i>Inst.</i>	<i>m</i>	<i>n</i>	<i>p</i>	<i>New MILP</i>		
				<i>UB</i>	<i>LB</i>	<i>t (sec)</i>
ins09	500	75	25	0.008548	0.006226	650
ins10	1000	100	20	0.015568	0.007452	760
ins11	1000	100	50	0.003187	0.002692	566
ins12	1000	150	35	0.005276	0.003240	1348
ins13	2000	100	20	0.021249	0.007846	1577
ins14	2000	100	35	0.007164	0.004684	1416
ins15	2000	200	50	0.003387	0.002093	5679
ins16	2000	200	75	0.001916	0.001436	6509
ins17	5000	200	25	0.021089	0.004764	3390
ins18	5000	200	50	0.004493	0.002362	13178
ins19	5000	250	75	0.002242	0.001416	21780
ins20	5000	250	100	0.001429	0.001078	10509
ins21	6000	200	100	0.001475	0.001184	9685
ins22	6000	250	100	0.001570	0.001068	6762
ins23	7000	200	100	0.001530	0.001193	8056
ins24	7000	250	100	0.001580	0.001089	1543
ins25	8000	250	100	0.001721	0.001094	1350
ins26	8000	300	100	0.001594	0.001003	3786
ins27	9000	250	100	0.001681	0.001100	9781
ins28	9000	300	100	0.002105	0.001046	546
ins29	10000	300	100	0.002001	0.001018	462
ins30	10000	300	150	0.001039	0.000690	532
ins31	11000	300	150	0.001001	0.000699	406
ins32	12000	300	150	0.001109	0.000696	410
ins33	13000	300	150	0.000958	0.000702	499
ins34	14000	350	150	0.001152	0.000664	643
ins35	15000	350	150	0.001243	0.000685	713
ins36	16000	400	200	0.000820	0.000486	643
ins37	17000	400	200	0.000723	0.000489	765
ins38	18000	450	200	0.000854	0.000472	744
ins39	19000	450	250	0.000621	0.000378	835
ins40	20000	500	250	0.000634	0.000371	923

The proposed method has the obvious potential to be applied to similar problems that arise from exploration of online social networks. Construction of some exact method based on this formulation is other possible direction of future work.

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