

# Convergence Rate of Projected Subgradient Method with Time-varying Step-sizes

Zhihan Zhu · Yanhao Zhang · Yong Xia

Received: date / Accepted: date

**Abstract** We establish the optimal ergodic convergence rate for the classical projected subgradient method with time-varying step-sizes. This convergence rate remains the same even if we slightly increase the weight of the most recent points, thereby relaxing the ergodic sense.

**Keywords** Subgradient method · step-size · ergodic convergence rate · nonsmooth convex optimization

**Mathematics Subject Classification (2000)** 90C25, 90C30

## 1 Introduction

Consider the nonsmooth convex optimization problem

$$x^* \in \operatorname{argmin}_{x \in \mathcal{X}} f(x),$$

where  $\mathcal{X} \subset \mathbb{R}^n$  is a compact convex set that is contained within the Euclidean ball  $B(x^*, R)$ , and  $f$  is (possibly nonsmooth) convex and Lipschitz on  $\mathcal{X}$ , i.e., there is an  $L > 0$  such that  $\|g\| \leq L$  for any  $g \in \partial f(x) \neq \emptyset$  and  $x \in \mathcal{X}$ .

The classical projected subgradient method (PSG) iterates the following equations for  $t \geq 1$ :

$$\begin{cases} y_{t+1} = x_t - \eta_t g_t, \text{ where } g_t \in \partial f(x_t), \\ x_{t+1} = \operatorname{argmin}_{x \in \mathcal{X}} \|x - y_{t+1}\|. \end{cases}$$

Utilizing the following constant step size

$$\eta_s \equiv \frac{R}{L\sqrt{s}}, \quad s = 1, \dots, t, \quad (1)$$

---

Zhihan Zhu · Yanhao Zhang · Yong Xia (corresponding author)  
School of Mathematical Sciences, Beihang University, Beijing 100191, People's Republic of China. E-mail: {zhizhanzhu, yanhaozhang, yxia}@buaa.edu.cn

PSG achieves an optimal ergodic convergence rate (see, for example, [1–3]) expressed as <sup>1</sup>

$$f\left(\frac{\sum_{s=1}^t x_s}{t}\right) - f(x^*) \leq \frac{RL}{\sqrt{t}}. \quad (2)$$

A more practical approach is to use a step-size that monotonically decreases towards 0. One such time-varying step-size, motivated by (1) and suggested in [1,2], is expressed as follows:

$$\eta_s = \frac{R}{L\sqrt{s}}, \quad s = 1, \dots, t. \quad (3)$$

However, using this step size results in sub-optimal ergodic convergence rate [1,2], as it adds an additional  $\log(t)$  factor compared to the right-hand side of (2).

The contribution of this note is to demonstrate that PSG with the time-varying step-size (3) indeed achieves the following optimal convergence rate.

**Theorem 1** *PSG with the time-varying step-size (3) satisfies*

$$f\left(\frac{\sum_{s=1}^t x_s}{t}\right) - f(x^*) \leq \frac{3RL}{2\sqrt{t}}.$$

In Section 2, we present a more generalized convergence analysis, allowing us to provide some insightful observations.

## 2 Analysis

Consider PSG with a general step-size  $\eta_s$ , which is assumed to be positive and non-increasing. We can establish the following convergence rate.

**Theorem 2** *For any fixed  $k \geq -1$ , PSG with a positive and non-increasing step-size sequence  $\{\eta_s\}$  satisfies*

$$f\left(\frac{\sum_{s=1}^t \frac{1}{\eta_s^k} x_s}{\sum_{s=1}^t \frac{1}{\eta_s^k}}\right) - f(x^*) \leq \frac{\frac{R^2}{\eta_t^{k+1}} + L^2 \sum_{s=1}^t \frac{1}{\eta_s^{k-1}}}{2 \sum_{s=1}^t \frac{1}{\eta_s^k}}. \quad (4)$$

*Proof* According to the definition of subgradient, we have

$$\begin{aligned} f(x_s) - f(x^*) &\leq g_s^T (x_s - x^*) \\ &= \frac{1}{\eta_s} (x_s - y_{s+1})^T (x_s - x^*) \\ &= \frac{1}{2\eta_s} (\|x_s - y_{s+1}\|^2 + \|x_s - x^*\|^2 - \|y_{s+1} - x^*\|^2) \end{aligned} \quad (5)$$

$$\begin{aligned} &= \frac{1}{2\eta_s} (\|x_s - x^*\|^2 - \|y_{s+1} - x^*\|^2) + \frac{\eta_s}{2} \|g_s\|^2 \\ &\leq \frac{1}{2\eta_s} (\|x_s - x^*\|^2 - \|x_{s+1} - x^*\|^2) + \frac{\eta_s}{2} L^2, \end{aligned} \quad (6)$$

<sup>1</sup>  $f((\sum_{s=1}^t x_s)/t)$  can be replaced with  $\min_{s=1, \dots, t} f(x_s)$  based on similar analysis.

where (5) follows from the elementary identity  $2a^T b = \|a\|^2 + \|b\|^2 - \|a - b\|^2$ , and (6) holds since  $\|g_s\| \leq L$  and

$$\|y_{s+1} - x^*\|^2 \geq \|x_{s+1} - x^*\|^2,$$

which is implied by the projection theorem.

Consequently, we have

$$\begin{aligned} & \left( \sum_{s=1}^t \frac{1}{\eta_s^k} \right) \left( f \left( \frac{\sum_{s=1}^t \frac{1}{\eta_s^k} x_s}{\sum_{s=1}^t \frac{1}{\eta_s^k}} \right) - f(x^*) \right) \\ & \leq \sum_{s=1}^t \frac{1}{\eta_s^k} (f(x_s) - f(x^*)) \quad (\text{since } f \text{ is convex}) \\ & \leq \sum_{s=1}^t \frac{1}{2\eta_s^{k+1}} (\|x_s - x^*\|^2 - \|x_{s+1} - x^*\|^2) + \sum_{s=1}^t \frac{1}{2\eta_s^{k-1}} L^2 \quad (7) \\ & = \frac{1}{2\eta_1^{k+1}} \|x_1 - x^*\|^2 + \sum_{s=2}^t \left( \frac{1}{2\eta_s^{k+1}} - \frac{1}{2\eta_{s-1}^{k+1}} \right) \|x_s - x^*\|^2 \\ & \quad - \frac{1}{2\eta_t^{k+1}} \|x_{t+1} - x^*\|^2 + \sum_{s=1}^t \frac{1}{2\eta_s^{k-1}} L^2 \\ & \leq \frac{R^2}{2\eta_1^{k+1}} + \frac{R^2}{2} \sum_{s=2}^t \left( \frac{1}{\eta_s^{k+1}} - \frac{1}{\eta_{s-1}^{k+1}} \right) + \sum_{s=1}^t \frac{1}{2\eta_s^{k-1}} L^2 \quad (8) \\ & = \frac{R^2}{2\eta_t^{k+1}} + \sum_{s=1}^t \frac{1}{2\eta_s^{k-1}} L^2, \end{aligned}$$

where (7) follows from (6), and (8) holds since  $1/\eta_s^{k+1} - 1/\eta_{s-1}^{k+1} \geq 0$  when  $k \geq -1$ . The proof is complete.  $\square$

**Remark 1** By setting  $k = -1$  in Theorem 2, the upper bound on the right-hand side (4) simplifies to

$$\frac{R^2 + L^2 \sum_{s=1}^t \eta_s^2}{2 \sum_{s=1}^t \eta_s},$$

which is exactly the same as the result presented in [1]. Then PSG with the time-varying step-size (3) satisfies

$$f \left( \frac{\sum_{s=1}^t \frac{1}{\sqrt{s}} x_s}{\sum_{s=1}^t \frac{1}{\sqrt{s}}} \right) - f(x^*) \leq \frac{2RL + RL \log t}{4(\sqrt{t+1} - 1)}, \quad (9)$$

which is sub-optimal. Note that computing the weighted average of the iterates in the second half of the sequence yields the optimal convergence rate [4, Corollary 3.2].

**Remark 2** *By setting  $k = 0$  in Theorem 2, we can immediately obtain the optimal convergence rate, as presented in Theorem 1.*

**Remark 3** *By setting any  $k$  such that  $k > -1$  in Theorem 2, the convergence rate of  $f((\sum_{s=1}^t x_s/\eta_s^k)/(\sum_{s=1}^t 1/\eta_s^k)) - f(x^*)$  will be  $\mathcal{O}(1/\sqrt{t})$ , without the presence of a  $\log t$  factor. In comparison with the sub-optimal case (9), when  $k > 0$ , the weighting scheme  $(\sum_{s=1}^t x_s/\eta_s^k)/(\sum_{s=1}^t 1/\eta_s^k)$  assigns smaller weights to the initial points and larger weights to the most recent points. This new result can be referred to as the “weak” ergodic convergence rate.*

**Remark 4** *We can apply the same proof techniques to extend the conclusion of weak ergodic convergence to mirror descent, Nesterov’s dual averaging, and other schemes with time-varying step sizes for solving nonsmooth convex optimization, see [1, 2].*

## Funding

This research was supported by National Key R&D Program of China under grant 2021YFA1003300, the National Natural Science Foundation of China under grant 12171021, and the Fundamental Research Funds for the Central Universities.

## Data Availability

The manuscript has no associated data.

## References

1. Y. Nesterov, Lectures on convex optimization, volume 137, Springer, 2018.
2. S. Bubeck, Convex optimization: Algorithms and complexity. Foundations and Trends Trends® in Machine Learning, 8(3-4): 231-357, 2015.
3. P. Rigollet, K. Li, Convex optimization for machine learning. Massachusetts Institute of Technology: MIT OpenCouseWare, <https://ocw.mit.edu/>, Oct. 2015.
4. G. Lan, First-order and Stochastic Optimization Methods for Machine Learning, Springer-Nature, 2020