

A Randomized Algorithm for Sparse PCA based on the Basic SDP Relaxation

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Abstract

Sparse Principal Component Analysis (SPCA) is a fundamental technique for dimensionality reduction, and is NP-hard. In this paper, we introduce a randomized approximation algorithm for SPCA, which is based on the basic SDP relaxation. Our algorithm has an approximation ratio of at most the sparsity constant with high probability, if called enough times. Under a technical assumption, which is consistently satisfied in our numerical tests, the average approximation ratio is also bounded by $\mathcal{O}(\log d)$, where d is the number of features. We show that this technical assumption is satisfied if the SDP solution is low-rank, or has exponentially decaying eigenvalues. We then present a broad class of instances for which this technical assumption holds. We also demonstrate that in a covariance model, which generalizes the spiked Wishart model, our proposed algorithm achieves a near-optimal approximation ratio. We demonstrate the efficacy of our algorithm through numerical tests on real-world datasets.

Key words: Sparse PCA, Randomized algorithm, Semidefinite Programming

1 Introduction

The Principal Component Analysis (PCA) problem involves finding a linear combination of d features that captures the maximum possible variance in a given $d \times d$ data matrix A . Formally, the problem is defined as

$$\max x^\top A x \quad \text{s.t.} \quad \|x\|_2 = 1. \quad (\text{PCA})$$

PCA is a widely used statistical technique for reducing the dimensionality of large datasets, and it has been successfully applied to a broad range of topics, including neuroscience, meteorology, psychology, genetics, finance, and pattern recognition. For a comprehensive overview of the applications of PCA, we refer interested readers to [26].

Despite its usefulness, the interpretation of a solution to PCA is limited since the principal component (PC) is often a linear combination of all d features. To address this issue, the Sparse Principal Component Analysis problem (SPCA) is introduced. SPCA aims to find a *sparse* linear combination of features while capturing the maximum variance. SPCA is formally defined as:

$$\max x^\top A x \quad \text{s.t.} \quad \|x\|_2 = 1, \quad \|x\|_0 \leq k. \quad (\text{SPCA})$$

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Here k is the *sparsity constant*, a positive integer that sets an upper bound on the number of non-zero entries in the d -dimensional vector x . Compared with PCA, using SPCA for dimensionality reduction yields more interpretable components, lowers downstream memory and computational costs, and helps prevent overfitting. SPCA has a wide range of real-world applications, such as identifying influential single-nucleotide polymorphisms in genetics [31], selecting informative object features in computer vision [35], and organizing a large corpus of text data in data science [46].

SPCA is an NP-hard problem in general [33], making it computationally challenging in practice. In fact, it is NP-hard to approximate SPCA within a multiplicative ratio of $(1 + \epsilon)$ for some constant $\epsilon > 0$ [11]. Despite the hardness of the problem, many polynomial-time approximation algorithms have been proposed to tackle SPCA. For instance, [37] accelerated SPCA by replacing the input matrix with its rank- m approximation formed from the top m eigenpairs, resulting an algorithm with a running time $\mathcal{O}(d^{m+1} \log d)$ and an approximation ratio $1/(1 - \delta_m)$, with $\delta_m \leq \lambda_{m+1} \cdot \min\{d/(k\lambda_1), 1/\max_{i \in [d]} A_{ii}\}$. This algorithm has the advantage that if the eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d$ of A satisfy an exponential decay, i.e., $\lambda_{i+1}/\lambda_i \leq c \in (0, 1)$, then δ_m decreases exponentially as m increases. [32] introduced two polynomial-time k -approximation algorithms: the Greedy algorithm and the Local Search algorithm. [12] introduced an ϵ -additive approximation algorithm with a runtime of $\mathcal{O}(d^{\text{poly}(1/\epsilon)})$ based on the previous work [3]. Moreover, [12] also proposed a simple $\min\{\sqrt{k}, d^{1/3}\}$ -approximation algorithm for SPCA, which is, to the best of our knowledge, the best known approximation ratio for SPCA algorithms with polynomial runtime.

Our contributions. In this paper, we propose a randomized algorithm based on the *basic* semidefinite programming (SDP) relaxation to SPCA,

$$\max \text{tr}(AW) \quad \text{s.t.} \quad \text{tr}(W) = 1, \|W\|_1 \leq k, W \succeq 0. \quad (\text{SPCA-SDP})$$

Our algorithm is not only efficient, but also improves upon the best known polynomial-time benchmark of $\min\{\sqrt{k}, d^{1/3}\}$ across a variety of practically motivated instances.

Efficient SDP-based Randomized Rounding with Provable Guarantees. Our algorithm transforms an (approximate) optimal solution W^* of SPCA-SDP into a feasible solution for SPCA, in time $\mathcal{O}(d \log d)$. Despite its efficiency, our algorithm achieves an approximation ratio that is upper bounded by k with high probability when run for $\Omega(d/k)$ many independent times, matching the guarantees of the Greedy algorithm and the Local Search algorithm in [32]. The average approximation ratio can be further upper bounded by $\mathcal{O}(\log d)$ under mild assumption on k and a technical assumption related to sum of square roots of diagonal entries of W^* . We note that in the regime where $k = \Omega(\log^2 d)$, and where the technical assumption is true, our algorithm admits an average approximation error strictly better than the best-known polynomial-time guarantee $\min\{\sqrt{k}, d^{1/3}\}$. We further show that this technical assumption is true if the rank of W^* is fixed, or W^* admits exponentially decaying eigenvalues. We further identify two classes of instances that guarantee a rank-one optimal solution, and hence satisfy the technical assumption: (i) Rank-one input matrices whose non-zero entries are bounded below by a certain value; (ii) General input matrices with a sufficient eigenvalue gap, a uniform contraction condition, and small entries outside a specific index set. To the best of our knowledge, we provide the first deterministic classes of instances in which SPCA-SDP admits rank-one optimal solutions. We also perform extensive numerical experiments, demonstrating the effectiveness of our proposed algorithm in real-world datasets. Oftentimes, our algorithm can find a solution which is as good as the best solution other existing methods studied in [12, 37, 32, 4, 21] can find. In terms of the runtime for SPCA-SDP, although general-purpose SDP solvers scale poorly, we find that the GPU implementation of an approximation algorithm [45] proves remarkably efficient: it finds W^* on $d = 2000$ instances of SPCA-SDP in under six seconds.

Adversarial-Robust Recovery Guarantees. We show that SPCA-SDP is robust to adversarial

perturbations in a general covariance model. Specifically, we consider a scenario where the input matrix A is under adversarial attack, i.e., $A = (B + M)^\top(B + M)$, where B represents the data matrix that has i.i.d. rows sampled from a covariance model having a sparse spike, and M represents an adversarial perturbation. We show that SPCA-SDP still yields an optimal solution close to the sparse spike when the sample size is sufficiently large. This generalizes the findings of [23] and provides further insight into the strong computational performance of SPCA-SDP. Under this model, our algorithm achieves an approximation ratio near one, indicating that even if the technical assumption for our randomized algorithm is not met, SPCA-SDP and our algorithm can still perform exceptionally well across diverse inputs.

Organization of this paper. In Section 2, we provide an overview of related work. In Section 3, we introduce our randomized algorithm for solving SPCA and provide theoretical results on approximation guarantees. In Section 4, we define a general statistical model that considers adversarial perturbation, demonstrate the robustness of SPCA-SDP against such perturbations, and provide an approximation bound for our algorithm within this model. In Section 5, we present numerical experiments conducted on various real-world datasets to evaluate the performance of our algorithm and compare with other algorithms. We defer proofs in Sections 3 and 4 to Sections 6 and 7. For the remainder of the section, we introduce the notation used in the paper.

Notation. Sets, vectors, and matrices: For any positive integer d , we define $[d] := \{1, 2, \dots, d\}$. Let x be a d -vector. The *support* of x is the set $\text{Supp}(x) := \{i \in [d] : x_i \neq 0\}$. Given an index set $\mathcal{I} \subseteq [d]$, denote by $x_{\mathcal{I}}$ the sub-vector of x indexed by \mathcal{I} , and we write $x_i := x_{\{i\}}$. For $1 \leq p \leq \infty$, we denote the p -norm of x by $\|x\|_p$. The 0-(pseudo)norm of x is $\|x\|_0 := |\text{Supp}(x)|$. We say that x is k -sparse if $\|x\|_0 \leq k$. Let M be a $m \times n$ matrix. Given two index sets $\mathcal{I} \subseteq [m]$, $\mathcal{J} \subseteq [n]$, we denote by $M_{\mathcal{I}, \mathcal{J}}$ the submatrix of M consisting of the entries in rows \mathcal{I} and columns \mathcal{J} . Let X be an $m \times m$ symmetric positive semidefinite matrix, i.e., $X \succeq 0$, denote by $Y := \sqrt{X}$ the *matrix square root* of X , i.e., $Y = Y^\top \succeq 0$ and $X = YY$. For $1 \leq p, q \leq \infty$, the p -to- q norm of M is defined as $\|M\|_{p \rightarrow q} := \max_{\|x\|_p=1} \|Mx\|_q$. The 2-norm of M is defined by $\|M\|_2 = \|M\|_{2 \rightarrow 2}$. The 1-norm of M is defined by $\|M\|_1 = \sum_{i,j} |M_{ij}|$. The infinity norm of M is defined by $\|M\|_\infty := \max_{i,j} |M_{ij}|$. The Frobenius norm of M is defined as $\|M\|_F := \sqrt{\sum_{i,j} |M_{ij}|^2}$.

Approximation ratio and ϵ -approximate solution: Let w^* be an optimal solution to a maximization problem \mathcal{P} with objective function f and input D . We say a (randomized) algorithm \mathcal{A} is an approximation algorithm to \mathcal{P} with an *approximation ratio* r , if \mathcal{A} can output a random solution \tilde{w} with input D such that $\mathbb{E}f(\tilde{w}) \geq 1/r \cdot f(w^*)$. Sometimes we will also say that \mathcal{A} is an r -approximation algorithm for brevity. We say a solution \tilde{w} is an ϵ -approximate solution to \mathcal{P} if \tilde{w} is feasible to \mathcal{P} such that $f(\tilde{w}) \geq f(w^*) - \epsilon$.

2 Related work

In this section, we discuss the literature related to our work. First, we discuss results related to the basic SDP relaxation, SPCA-SDP. It is known that SDP can be solved in polynomial time up to an arbitrary accuracy, by means of the ellipsoid algorithm and interior point methods [39, 30]. The basic SDP relaxation SPCA-SDP was initially proposed in [15] and has been extensively researched since then. The literature includes studies on its performance under various statistical models and its approximability. The statistical performance of SPCA-SDP has been thoroughly investigated, with the assumption that $A = B^\top B$ and B being an $n \times d$ matrix. For example, [1] demonstrated that the *sparse spike*, which is the sparse maximal eigenvector, can be recovered in a particular covariance model, known as the Wishart spiked model, when the number of samples n is above the threshold $\Omega(k \log d)$. Then, [28] showed that SPCA-SDP is unable to recover the sparse spike

if $k = \Omega(\sqrt{n})$ in the model discussed in [1]. In a more general spiked covariance model, [44] showed that SPCA-SDP can recover the sparse spike but at a slightly higher sample complexity $\Omega(k^2 \log d)$. Additionally, [23] demonstrated that SPCA-SDP is robust to adversarial perturbations in the Wishart spiked model. Moreover, a streamline of work [5, 6] investigated the information theoretical limits of SPCA-SDP recovering the sparse spike in certain covariance models. Regarding approximation results, an approximation algorithm based on SPCA-SDP was developed in [13]. It is worth noting that authors of [13] acknowledged that their theoretical guarantees may not be indicative of the outstanding practical performance of their algorithm. Nevertheless, they provided compelling empirical evidence of its efficacy by showcasing impressive computational results on diverse real-world datasets. A worst-case approximation bound of SPCA-SDP was studied in [12], revealing that there exists an instance that results in an approximation ratio that is quasi-quasi-polynomial in d .

Then, we discuss efficient algorithms for SPCA in the literature. To the best of our knowledge, there are currently five other main categories of methods for finding (approximate) solutions to SPCA, except via its basic SDP relaxation. Firstly, various existing methods solve SPCA by relaxing the sparsity constraint with a convex constraint. These methods include providing practical algorithms to maximize the objective value in an ℓ_1 ball [19], or by solving stronger SDP relaxations [27]. Secondly, methods based on integer programming have been developed to solve SPCA exactly or approximately, including using integer programs to obtain dual bounds, for either single sparse PC [20] or multiple but row-sparse PCs [21], solving mixed-integer SDPs or mixed-integer linear programs [32], using branch-and-bound algorithm to obtain certifiable (near) optimality [4, 7], and combining integer programs with geometric approach to obtain multiple sparse PCs [8]. Thirdly, polynomial-time algorithms for a fixed rank input matrix A are proposed, either for a single sparse PC [37], or for multiple but row-sparse PCs [16]. It should be noted that the complexity of these algorithms are oftentimes exponential in $\text{rank}(A)$. Fourthly, polynomial running-time approximation algorithms for SPCA have been developed, including finding a low rank approximation of A and then solving SPCA exactly [37], deriving an approximation algorithm via basis truncation [12], and via basic SDP relaxation [13]. The fifth category includes methods for solving SPCA in certain statistical models via different approaches, including covariance thresholding method [18] and sub-exponential algorithms [22]. A recent work [17] introduces a plug-and-play framework to provide speedup to these existing algorithms in the categories by first finding block-diagonal approximation to the input matrix A and then solving SPCA sub-problems inside each block. For a more comprehensive review of the literature in each of the categories mentioned above, interested readers are referred to the cited papers.

Note that some of the aforementioned work have established approximation results using non-convex optimization methods, which may necessitate an exponential runtime. The non-convexity comes from the fact that the authors solve a maximization problem of a convex objective. For instance, the authors of [20] have demonstrated that by relaxing SPCA within an ℓ_1 ball, an upper bound for SPCA with constant approximation ratio can be achieved. In [21], the authors have extended these findings to finding m sparse principal components with a global support, with an approximation ratio $\mathcal{O}(\sqrt{\log m})$.

3 A randomized algorithm for SPCA

In this section, we present our randomized approximation algorithm for SPCA. For brevity, we denote an ϵ -approximate optimal solution to SPCA-SDP as W^* and an optimal solution to SPCA as x^* , for the rest of this paper.

We begin by presenting the motivation. Although SPCA-SDP has nice properties, such as the result in [32], where the authors demonstrate that the objective value of an optimal solution to SPCA-SDP is at most k times that of SPCA, there are several limitations that hinder the practical application of SPCA-SDP. For instance, as pointed out in [18], that there are also some theoretical limitations of SPCA-SDP. Specifically, (i) W^* is not guaranteed to be a rank-one matrix in general; and (ii) in some cases where W^* is rank-one, denoted as $W^* = v^*(v^*)^\top$, but oftentimes the zero-(pseudo)norm of v , $\|v\|_0$, is larger than k . This raises a natural question: is there a way to transform W^* into a feasible solution for SPCA with high quality?

In [13], the authors partially address this question by providing a vector z , obtained by finding the best rank-one approximation uu^\top to W^* , keeping the $\mathcal{O}(k^2/\epsilon^2)$ largest components (in absolute value) in u , and setting the other entries to zero. They obtain that $z^\top Az \geq 1/\alpha \cdot (x^*)^\top Ax^* - \epsilon$, where $\alpha \geq 1$ is the ratio $\text{tr}(AW^*)/u^\top Au$. However, this algorithm has two major issues: (a) z is generally not a k -sparse vector and $\|z\|_0$ could be much larger than k ; and (b) there is no clear theoretical bound on α , making it difficult for users to predict the worst-case quality of z .

In this section, we present Algorithm 1 as an approximation algorithm for SPCA-SDP with the aim of obtaining a high-quality k -sparse vector from W^* and addressing the issues discussed above. The main idea behind Algorithm 1 is to treat the diagonal entries in W^* and A as probability masses that determine whether or not to include the corresponding entry in the support of a vector x .

Algorithm 1 Randomized Algorithm for SPCA

Require: A matrix $A \in \mathbb{R}^{d \times d}$, a positive semidefinite matrix $W \in \mathbb{R}^{d \times d}$, and a positive integer k

Ensure: A vector $z \in \mathbb{R}^d$, such that $\|z\|_2 = 1$ and $\|z\|_0 \leq k$ with high probability

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1: for  $i = 1$  to  $d$  do
2:    $a_i \leftarrow \sqrt{W_{ii}}$ 
3: for  $i = 1$  to  $d$  do
4:    $p_i \leftarrow \min\{1, 2/3 \cdot ka_i / \sum_{j=1}^d a_j + 1/12 \cdot kA_{ii} / \text{tr}(A)\}$ 
5:   Sample independently  $\epsilon_i \leftarrow 1$  with probability  $p_i$ , and  $\epsilon_i \leftarrow 0$  with probability  $1 - p_i$ 
6:    $S \leftarrow \{i \in [d] : \epsilon_i = 1\}$ ,  $z \leftarrow$  zero vector in  $\mathbb{R}^d$ 
7:   if  $A \succeq 0$  and  $|S| < k$  then
8:      $S \leftarrow S \cup T$ , with  $T \cap S = \emptyset$  and  $|T| = k - |S|$ 
9:      $z_S \leftarrow \arg \max_{\|y\|_2=1} y^\top A_{S,S} y$ 
10: return  $z$ 

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In Algorithm 1, lines 7-9 aim to find a better solution. Here, the method of determining set $T \subseteq [d] \setminus S$ on line 8 is omitted, as it does not affect the theoretical bound discussed in the next section. Note that, except for line 8, Algorithm 1 simply requires a runtime at most $\mathcal{O}(d + k^2 \log k)$ (assuming line 9 is solved through randomized Lanczos method [38]). In Section 5, we introduce a very simple heuristic to determine T in time $\mathcal{O}(d \log d)$.

In practice, one can call Algorithm 1 several times, with the intension to obtain a better solution. The operational procedures are presented in Algorithm 2. Approximation guarantee for these algorithms will be provided in the subsequent sections.

Note that lines 1-2 in Algorithm 2 give a greedy heuristic and guarantee that Algorithm 2 finds one feasible solution to SPCA. It is very powerful in some statistical models, as we will see in Section 4.

Algorithm 2 Multi-run Randomized Algorithm for SPCA

Require: A matrix $A \in \mathbb{R}^{d \times d}$, a positive semidefinite matrix $W \in \mathbb{R}^{d \times d}$, a positive integer $k \leq d$, the number of calling N of Algorithm 1

Ensure: A unit vector $z \in \mathbb{R}^d$, such that $\|z\|_0 \leq k$ with high probability

- 1: $S_0 \leftarrow$ the set of indices in $[d]$ that corresponds to the k largest diagonal entries in W
 - 2: $z_0 \leftarrow \arg \max_{\|y\|_2=1} y^\top A_{S_0, S_0} y$
 - 3: **for** $i = 1$ **to** N **do**
 - 4: Obtain z_i using Algorithm 1 with input (A, W, k)
 - 5: **return** the best feasible solution to SPCA among $\{z_i\}_{i=0}^N$
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3.1 Approximation guarantees

In this section, we establish approximation bounds for Algorithms 1 and 2. We first show that, if $N = \Omega(d/k)$, Algorithm 2 is a k -approximation algorithm with probability at least 99%.

Theorem 1. *Let x^* be an optimal solution to SPCA with input pair (A, k) , where we assume $A \in \mathbb{R}^{d \times d}$ is positive semidefinite, and k is a positive integer such that $k \leq d$. Let W^* be an ϵ -approximate optimal solution to SPCA-SDP with input pair (A, k) . Let z be the output of Algorithm 2 with input tuple (A, W^*, k, N) .*

Then, one could obtain an approximate solution z to SPCA such that $z^\top A z \geq (x^)^\top A x^* / k$ with probability at least $1 - \exp\{-kN/(12d)\} - \exp\{-ckN\}$ for some absolute constant $c > 0$.*

Then, we show that the approximation ratio of Algorithm 1 is also upper bounded by a $\mathcal{O}(\log d/k)$ multiple of the *sum of square roots* (SSR) of diagonal entries of W^* , i.e., $\sum_{i=1}^d \sqrt{W_{ii}^*}$. Due to the intricate technical details, we present an informal statement of the result as follows. A formal statement can be found in Section 6.1. Additionally, the formal theorem there is more comprehensive, demonstrating that Algorithm 1 remains effective even when A is indefinite.

Theorem 2 (Informal version of Theorem 13). *Let x^* be an optimal solution to SPCA with input pair (A, k) , where we assume $A \in \mathbb{R}^{d \times d}$ is positive semidefinite with $\|A\|_2 = 1$, and k is a positive integer such that $k \leq d$. Let W^* be an ϵ -approximate optimal solution to SPCA-SDP with input pair (A, k) . Denote z to be the output of Algorithm 1 with input tuple (A, W^*, k) . Then, there exists a random event $\mathcal{R} \subseteq \{\|z\|_0 \leq k\}$ such that $\mathbb{P}(\mathcal{R}) \geq 1 - \exp\{-ck\} - 2d^{-3}$ for an absolute constant $c > 0$, and such that when $ck \geq 3 \log(d/k) + \log \log d$, one has*

$$C \log d \cdot \left[1 + \frac{9(\sum_{i=1}^d \sqrt{W_{ii}^*})^2}{4k} \right] \cdot \mathbb{E}[z^\top A z | \mathcal{R}] \geq \left[1 - \mathcal{O}\left(\frac{1}{\log d}\right) \right] (x^*)^\top A x^* - \epsilon,$$

for some absolute constant $C > 0$.

Remark. *In this remark, we discuss the approximation ratio of Algorithm 1 in Theorem 2. On one hand, in Theorem 2, we obtain a worst-case multiplicative ratio $\mathcal{O}(d \log d/k)$ due to the fact that $\text{tr}(W^*) = 1$ and Cauchy-Schwarz inequality. On the other hand, it is worth noting that when*

$$\text{SSR} := \sum_{i=1}^d \sqrt{W_{ii}^*} \leq c_0 \cdot \sqrt{k} \tag{1}$$

for some absolute constant $c_0 > 0$, Algorithm 1 can obtain a multiplicative ratio $\mathcal{O}(\log d)$. When $k = \Omega(\log^2 d)$, implying $k \geq 3 \log(d/k) + \log \log d$, this $\mathcal{O}(\log d)$ guarantee strictly surpasses the $\min\{\sqrt{k}, d^{1/3}\}$ -approximation of [12], which, to our knowledge, is the smallest ratio previously known for any polynomial-time SPCA algorithm. We note that, while (1) might not always hold,

it is easily checkable once SPCA-SDP is solved, which could be done in polynomial time. In Section 3.2, we provide further discussions about assumptions on W^* such that (1) holds, and in Section 3.3, we provide classes of instances where (1) holds for $c_0 = 1$. Furthermore, as we will see in Section 5, (1) oftentimes holds in our numerical tests (in fact, $c_0 \leq 2.21$ for 80% of the instances).

Remark. In this remark, we point out that Theorem 2 in fact holds true for any $W^* \succeq 0$ such that $\text{tr}(W^*) = 1$ and $\text{tr}(AW^*) \geq (x^*)^\top Ax^* - \epsilon$. This implies that our algorithm extends to any SDP relaxation stronger than SPCA-SDP. For instance, our rounding scheme applies to the tighter relaxation of [27] and preserves the guarantees of Theorem 2. We nevertheless focus on SPCA-SDP for two main reasons. From a theoretical perspective, stronger relaxations do not necessarily yield better SPCA solutions in the input families studied in Sections 3.3 and 4, the latter being a standard model in the statistics literature [1, 28, 44]. From a computational perspective, SPCA-SDP can be (approximately) solved in seconds with a GPU implementation of the CGAL method [45], whereas most stronger relaxations might not be compatible with CGAL and thus scale poorly.

Note that Theorem 2 gives only an expected approximation guarantee for Algorithm 1. In practice, running Algorithm 2 with a large enough N and returning the best result gives, with high probability, an approximation ratio matching that expectation. The necessary sample size could be found directly from Hoeffding's inequality (see Theorem 4.12 in [34]).

3.2 Assumptions on W^* yielding small sum of square roots

In this section, we discuss assumptions on W^* that yield small SSR, i.e., $\sum_{i=1}^d \sqrt{W_{ii}^*}$, where W^* is an (approximate) optimal solution to SPCA-SDP. In the first proposition, we will show that if SPCA-SDP admits a sparse optimal solution W^* , then the SSR is upper bounded by the support of diagonal entries of W^* . Then, we generalize this result to general low-rank optimal solutions, and show that the SSR is upper bounded by \sqrt{rk} , where $r := \text{rank}(W^*)$. In this case, Algorithm 1 gives an average approximation ratio of order $\mathcal{O}(r \log d)$. We also note that this result could be very helpful in practice—it is possible to obtain a fixed-rank approximate solution to SPCA-SDP via CGAL [45] with a fixed number of iterations and a low-rank initial primal solution, or to obtain a local low-rank solution to SPCA-SDP via the first-order approach proposed by Burer and Monteiro [9, 10, 14], or via accelerated first-order methods [43]. Finally, we show that under certain assumptions, SSR is small even when W^* is of full rank. We give our first proposition stating that a sparse W^* has a small SSR:

Proposition 3. *Let $W \succeq 0$, and assume that $\text{tr}(W) = 1$. Define the diagonal support of W as $\text{DSupp}(W) := \{i \in [d] : W_{ii} \neq 0\}$. Then, $\text{SSR} = \sum_{i=1}^d \sqrt{W_{ii}} \leq \sqrt{|\text{DSupp}(W)|}$.*

Proof. By Cauchy-Schwarz inequality, $\sum_{i=1}^d \sqrt{W_{ii}}$ is at most $\sqrt{|\text{DSupp}(W)|}$. \square

Note that a solution W^* with sparse diagonal support is by definition a low-rank matrix. We now provide an upper bound for SSR to general low-rank feasible solutions to SPCA-SDP:

Proposition 4. *Let $W \succeq 0$, and assume that $\text{tr}(W) = 1$, $\|W\|_1 \leq k$, and $\text{rank}(W) = r$. Then, $\text{SSR} = \sum_{i=1}^d \sqrt{W_{ii}} \leq \sqrt{rk}$.*

Proof. Suppose that $W = YY^\top$ with $Y \in \mathbb{R}^{d \times r}$. Write $Y^\top = (y_1, y_2, \dots, y_d)$, with $y_i \in \mathbb{R}^r$. It is clear that $W_{ij} = y_i^\top y_j$ for any $i, j \in [d]$. For ease of notation, we define $r_i := \|y_i\|_2$ and $u_i := y_i/r_i$. Then, we see that $\text{SSR} = \sum_{i=1}^d \sqrt{W_{ii}} = \sum_{i=1}^d r_i$ and $\|W\|_1 = \sum_{i,j=1}^d r_i r_j |u_i^\top u_j|$.

We use a probabilistic viewpoint to lower bound $\|W\|_1$ by SSR^2/r . Let $I, J \in [d]$ be two i.i.d. random variables with $\mathbb{P}(I = i) = r_i/\text{SSR}$, and it is clear that

$$\|W\|_1 = \text{SSR}^2 \mathbb{E}[u_I^\top u_J] \geq \text{SSR}^2 \mathbb{E}[u_I^\top u_J]^2 = \text{SSR}^2 \mathbb{E}(u_I^\top u_J)(u_J^\top u_I) = \text{SSR}^2 \text{tr} \left((\mathbb{E} u_I u_I^\top)^2 \right),$$

where the inequality follows by the fact that $|u_I^\top u_J| \leq 1$. Define the matrix $G := \mathbb{E} u_I u_I^\top \in \mathbb{R}^{r \times r}$, and let $\lambda_i(G)$ be the i -th largest eigenvalue of G , we obtain that

$$\text{tr}(G^2) = \sum_{i=1}^r \lambda_i(G)^2 = \frac{r \cdot \sum_{i=1}^r \lambda_i(G)^2}{r} \geq \frac{(\sum_{i=1}^r \lambda_i(G))^2}{r} = \frac{1}{r}$$

via Cauchy-Schwarz inequality. \square

Finally, we show that, if the eigenvalues of W^* decays exponentially, then $\text{SSR} = \mathcal{O}(k \log d)$:

Proposition 5. *Suppose that there exists a constant $q \in (0, 1)$ such that the i -th largest eigenvalue of W , i.e., $\lambda_i(W)$, satisfies that $\lambda_i(W) \leq q^{i-1} \cdot \lambda_1(W)$ for all $i \in [d]$. Then, there exists an absolute constant $C > 0$ such that $\sum_{i=1}^d \sqrt{W_{ii}} \leq C \sqrt{k \log d / \log(1/q)}$.*

Proof. Let $W \succeq 0$ and assume that $\text{tr}(W) = 1$ and $\|W\|_1 \leq k$. Let the singular value decomposition of W be $\sum_{i=1}^d \lambda_i(W) u_i u_i^\top$. Define the orthogonal matrix $U := (u_1, u_2, \dots, u_d)$, and thus $U^{-1} = U^\top$ and hence $UU^\top = \sum_{i=1}^d u_i u_i^\top = I_d$. In other words, we have that $\sum_{j=1}^d (u_i)_j^2 = 1$ for any $i \in [d]$. Let r be the smallest integer such that $q^r \leq 1/d^2$, and thus $r = \lceil 2 \log d / \log(1/q) \rceil$. Write $W_1 := \sum_{i=1}^r \lambda_i(W) u_i u_i^\top$, and $W_2 := W - W_1 = \sum_{i=r+1}^d \lambda_i(W) u_i u_i^\top$. It is clear that

$$\sum_{j=1}^d \sqrt{W_{jj}} = \sum_{j=1}^d \sqrt{(W_1)_{jj} + (W_2)_{jj}} \leq \sum_{j=1}^d \left(\sqrt{(W_1)_{jj}} + \sqrt{(W_2)_{jj}} \right).$$

By Theorem 4, we obtain that $\sum_{j=1}^d \sqrt{(W_1)_{jj}} \leq \sqrt{rk} = \sqrt{\lceil 2k \log d / \log(1/q) \rceil}$. For the term involving W_2 , we see that $\sqrt{(W_2)_{jj}} = \sqrt{\sum_{i=r+1}^d \lambda_i(W) (u_i)_j^2} \leq \sqrt{1/d^2} = 1/d$. Therefore, we obtain that $\sum_{j=1}^d \sqrt{(W_2)_{jj}} \leq d \cdot \frac{1}{d} = 1$, and thus $\sum_{j=1}^d \sqrt{W_{jj}} \leq \sqrt{\lceil 2k \log d / \log(1/q) \rceil} + 1$. \square

3.3 Sufficient conditions for a rank-one optimal solution

In this section, we provide further understanding for the technical condition (1), by providing sufficient conditions for obtaining a rank-one optimal solution to SPCA-SDP. We note that while conditions of this type have been investigated in the context of general QCQPs [42], in this section we focus on conditions specifically tailored to SPCA-SDP. By Theorem 4, the SSR is upper bounded by \sqrt{k} when there is an rank-one (approximate) optimal solution to SPCA-SDP. To our knowledge, we give the first deterministic classes of instances for SPCA-SDP that guarantee rank-one optimal solutions.

We start by stating a simple fact that, if the input matrix A admits a maximum eigenvector with an ℓ_1 -norm upper bounded by \sqrt{k} , then SPCA-SDP admits a rank-one optimal solution.

Fact 1. *Let that $A \succeq 0$, and denote by $v_1(A)$ an eigenvector corresponding to the maximum eigenvalue of A with $\|v_1(A)\|_2 = 1$. Assume that $\|v_1(A)\|_1 \leq \sqrt{k}$, then $v_1(A)v_1(A)^\top$ is an optimal solution to SPCA-SDP.*

Proof. Let $W \succeq 0$ be a feasible solution to SPCA-SDP, and assume that its singular value decomposition is $W = \sum_{i=1}^d \lambda_i v_i v_i^\top$. Denote by $\lambda_1(A)$ the largest eigenvalue of A . It is clear that

$$\text{tr}(AW) = \sum_{i=1}^d \lambda_i v_i^\top A v_i \leq \sum_{i=1}^d \lambda_i \cdot \lambda_1(A) = \lambda_1(A),$$

where the last equality follows from the fact that $\text{tr}(W) = 1$. We obtain our desired result by noticing the fact that $\|v_1(A)v_1(A)^\top\|_1 = \|v_1(A)\|_1^2 \leq k$ and $\text{tr}(Av_1(A)v_1(A)^\top) = \lambda_1(A)$. \square

In the next example, we provide a class of instances that satisfy the assumptions in Fact 1:

Example. Suppose that the matrix $A = \lambda I - S \succeq 0$ for some $\lambda \geq 0$ and $S \succeq 0$. Denote by $\{n_i\}_{i=1}^r$ an orthonormal basis of the nullspace of S with dimension $r \leq d$, and denote by $N := (n_1, n_2, \dots, n_r)$. For $i \in [d]$, let $N_i \in \mathbb{R}^r$ be the row vector of N . Assume that $\sum_{i=1}^d \|N_i\|_2 \leq \sqrt{rk}$, then A admits a top eigenvector v such that $\|v\|_1 \leq \sqrt{k}$.

Proof. It only suffices to show that there exists a unit vector $x \in \mathbb{R}^r$ such that $\sum_{i=1}^d \left| \sum_{j=1}^r N_{ij}x_j \right| \leq \sqrt{k}$. Indeed, if such x exists, the vector Nx is by definition a top eigenvector of A with $\|Nx\|_2 = 1$ and $\|Nx\|_1 \leq \sqrt{k}$.

We use a probabilistic method to prove the desired result. Let $\{\epsilon_i\}_{i=1}^r$ be i.i.d. Rademacher random variables, i.e., $\mathbb{P}(\epsilon_i = \pm 1) = 1/2$. By Khintchine inequality [24], we obtain that $\mathbb{E} \left[\left| \sum_{j=1}^r N_{ij}\epsilon_j \right| \right] \leq \|N_i\|_2$, and therefore $\mathbb{E} \sum_{i=1}^d \left| \sum_{j=1}^r N_{ij}\epsilon_j \right| \leq \sum_{i=1}^d \|N_i\|_2 \leq \sqrt{rk}$. Hence, we see that there exists a vector $y \in \{\pm 1\}^r$ such that $\sum_{i=1}^d \left| \sum_{j=1}^r N_{ij}y_j \right| \leq \sqrt{rk}$. Taking $x = y/\sqrt{r}$ concludes the proof. \square

However, in practice, the assumptions in Fact 1 might not hold. In the remainder of the section, we provide other classes of instances that allow the top eigenvector of A to have a larger ℓ_1 -norm, yet still guarantees that SPCA-SDP admits a rank-one optimal solution. In the next theorem, we show that if A is the sum of a non-negative multiple of the identity and a rank-one matrix, then SPCA-SDP admits a rank-one solution under mild assumptions:

Theorem 6. Assume that $A = \lambda I_d + uu^\top$ for some vector $u \in \mathbb{R}^d$ with $m := \|u\|_1 / \|u\|_2 > \sqrt{k}$. Let $T := \text{Supp}(u)$, and assume that

$$\frac{m - \sqrt{k \cdot \frac{|T|-m^2}{|T|-k}}}{|T|} < \min_{i \in T} |u_i| < \frac{m + \sqrt{k \cdot \frac{|T|-m^2}{|T|-k}}}{|T|}. \quad (2)$$

Then, SPCA-SDP admits a unique optimal solution $w^*(w^*)^\top$ with $\text{Supp}(w^*) = T$.

We note that if A is of a fixed rank r (up to an addition of a scaling of identity), an optimal solution to SPCA could be found in polynomial time [37, 16]. In the next theorem, we generalize Theorem 6 to A with arbitrary rank, but satisfying stronger assumptions on its eigensystem:

Assumption 1. Suppose that there exists a set $S \subseteq [d]$. Let $A_{S,S}$ be the sub-matrix of A indexed by S with eigenvalues $\lambda_1 > \lambda_2 \geq \lambda_3 \geq \dots \geq \lambda_{|S|} \geq 0$. For each $i \in [|S|]$, let v_i denote the eigenvector corresponding to λ_i , where $\|v_i\|_2 = 1$. Define the sign vector of v_1 to be $s := \text{sign}(v_1)$, and write $\alpha_i := s^\top v_i$ for $i \in [|S|]$. Finally, we set $D := \sqrt{\frac{4\|v_1\|_1^4 - k\|v_1\|_1^2}{k \sum_{i=2}^{|S|} \alpha_i^2}}$. Then, we assume that

A1 (Sufficient eigengap). The first eigenvector v_1 satisfies $\|v_1\|_1 > \sqrt{k}$. Furthermore, we have $\left(1 - \frac{D}{1-\gamma} \cdot \frac{\sqrt{k \cdot |S|}}{\|v_1\|_1^2}\right) \lambda_1 \geq (D+1)\lambda_2$ for some $\gamma \in [0, 1)$.

A2 (Uniform contraction). We assume that $\text{Supp}(v_1) = S$. For all $j \in [|S|]$, and for all $\lambda \in [\lambda_1/(D+1), \lambda_1]$, we have $\gamma \|v_1\|_1 \cdot |v_{1,j}| \geq \left| \sum_{i=2}^{|S|} \frac{\lambda_1 - \lambda}{\lambda_i - \lambda} \alpha_i v_{i,j} \right|$.

A3 (Small entries outside S). We have that $\max\{\max_{i \in S, j \in S^c} |A_{ij}|, \max_{i, j \in S^c} |A_{ij}|\} \leq \frac{\delta}{2\sqrt{k}\|v_1\|_1^2}$, where $\delta > 0$ is a constant of v_i and λ_i such that $\frac{\|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_1}{\|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_2} \geq \sqrt{k}$ for any $\lambda \in [\lambda_1 - \delta, \lambda_1]$.

Loosely speaking, in A1, we ask that the input matrix A to have a sufficient gap between λ_1 and λ_2 . In A2, we ask the eigensystem of A behaves in a good way such that the right-hand-side admits a uniform contraction bound. The intuition behind this assumption is to make sure that the sign vector of our candidate optimal solution w^* would remain unchanged in a certain interval, where we believe that w^* would exist. The details would be made clear in the proofs in Section 6.2. Lastly, in A3, we ask that the entries of the input matrix A is small enough outside S , and we will prove that the constant $\delta > 0$ indeed exists in Theorem 15. We note that these assumptions would not make SPCA easier, as S might not be the support for an optimal solution to SPCA.

Next, we are ready to state the formal result:

Theorem 7. *Under Assumption 1, SPCA-SDP admits a rank-one optimal solution $W^* = w^*(w^*)^\top$, with $w^* \in \mathbb{R}^d$ and $\text{Supp}(w^*) = S$. Moreover, if the inequality in A1 in Assumption 1 is strict, then W^* is the unique optimal solution to SPCA-SDP.*

For a rank-one optimal solution W^* , we can apply Algorithm 2 for a set number of iterations to obtain a solution to SPCA with an approximation ratio of $\mathcal{O}(\log d)$, as guaranteed by Theorem 2. However, we acknowledge that, when W^* is rank-one, stronger approximation guarantees are achievable, as shown in [19, 21]. The authors demonstrate that solving specific non-convex quadratic programs, equivalent to enforcing a rank-one solution in SPCA-SDP, yields a solution with a constant approximation ratio, using a slightly different sampling rule compared to Algorithm 1. Despite some algorithmic overlap, our approach diverges significantly from theirs in several ways: (i) Algorithm 1 takes a square positive semidefinite input, while [19, 21] operates on vector solution(s); (ii) this distinction also leads to different proof techniques: [19, 21] analyze the size of feasible region, whereas we derive good-quality solutions based on properties of (sub-)Gaussian variables, as will be made clear in Section 6; and (iii) while their work focuses on efficiently solving non-convex programs (except exponential time complexity in the worst case), we aim to develop a polynomial-time algorithm with strong approximation ratios and identify input classes where even better performance can be achieved, as discussed in this and the following section.

4 Robustness of basic SDP relaxation within a general covariance model

In this section, we study a statistical model where the input matrix A is of the form $A = (B + M)^\top(B + M)$, where $B \in \mathbb{R}^{n \times d}$ is a data matrix with a certain sparse signal, and M is an adversarial perturbation matrix. Here, n is known to be the number of samples. One of the goals this section is to demonstrate that under this model assumption, W^* closely approximates a sparse signal embedded within the model. Consequently, W^* can be regarded as an effective approximation of the true sparse signal. After that, we show that in this model, our randomized algorithm Algorithm 2 achieves an approximation ratio close to one, suggesting our algorithm is also very effective.

In [23], the authors studied the spiked Wishart model, where M is a zero matrix, and B is a spiked standard Gaussian matrix, i.e., every row of B is an i.i.d. random vector drawn from $\mathcal{N}(0_d, I_d + \beta vv^\top)$, with $\beta > 0$ and v being a k -sparse vector. The authors demonstrated that an

optimal solution to SPCA-SDP provides a good approximation to v for a certain sample size n , which is roughly $\mathcal{O}(k \log d + k \|M\|_{1 \rightarrow 2}^2)$. However, such spiked assumption is often not applicable to real-life scenarios, as it is uncommon for each row of the actual data matrix B to represent a sum of a sparse signal realization $\sqrt{\beta}v$ and independent standard Gaussian noise. This discrepancy serves as the impetus for exploring the performance of SPCA-SDP in more generalized contexts. These contexts are characterized not only by the presence of sub-Gaussian random variables but also by the inclusion of multiple realizations of signals, amongst which a sparse dominant signal is present. Formally, we introduce Model 1:

Model 1. *The input matrix A can be written as $A = (B + M)^\top(B + M)$, where $B \in \mathbb{R}^{n \times d}$ is a random matrix with i.i.d. sub-Gaussian rows with parameter σ^2 , and M is a modification matrix such that its maximal column norm is upper bounded by a constant $b > 0$, i.e., $\|M\|_{1 \rightarrow 2} \leq b$. Furthermore, the rows of B have zero means and admit a covariance matrix Σ , such that Σ has a k -sparse maximal eigenvector v associated with eigenvalue λ_1 .*

We present in Theorem 9 that our algorithm achieves an approximation ratio close to one given a sufficient number of samples n . This result develops on the following characterization that W^* is close enough to vv^\top , implying that SPCA-SDP is robust to adversarial perturbations in Model 1:

Proposition 8. *In Model 1, denote λ_1, λ_2 to be the largest and second largest eigenvalue of Σ , respectively, and assume $\lambda_1 - \lambda_2 > 0$. Let v be the eigenvector associated with λ_1 , and denote $a := \min_{i: v_i \neq 0} |v_i|$. Let W^* be an optimal solution to SPCA-SDP. Then, there exists an absolute constant $C^* > 0$ such that when n is greater or equal to*

$$n^* := \max \left\{ C^* \cdot \left[\frac{k^2 \sigma^4 \log d + b^2 k^2 (\sigma^2 + \max \Sigma_{ii})}{(\lambda_1 - \lambda_2)^2 a^4} + \frac{kb^2}{(\lambda_1 - \lambda_2) a^2} \right], \frac{4}{a^2}, \log d \right\}, \quad (3)$$

then $\|W^ - vv^\top\|_\infty \leq a^2/2$ holds with probability at least $1 - d^{-10}$.*

Remark. *In this remark, we discuss the sample complexity required for SPCA-SDP to recover $\text{Supp}(v)$ in Model 1, which might be of independent interests. According to Theorem 8, given a fixed signal intensity $\lambda_1 - \lambda_2$, a fixed variance factor σ^2 , and a fixed a , if*

$$n = \Omega(k^2 \log d + k^2 b^2 \lambda_1 + kb^2 \log d), \quad (4)$$

one can find out $\text{Supp}(v)$ with high probability via SPCA-SDP. We note that the term $\Omega(k^2 \log d)$ in (4) is due to the recovery of $\text{Supp}(v)$ in Model 1 without any adversarial perturbation, which is consistent with the findings of [44]. The term $\Omega(k^2 b^2 \lambda_1 + kb^2 \log d)$ in (4) reflects the additional number of samples required to recover $\text{Supp}(v)$ under adversarial perturbations. Finally, we note that such sample complexity is insufficient to imply (1) via the use of Theorem 8 directly.

We are ready to develop the main theorem in this section. The core message is that the greedy heuristic (lines 1 - 2) in Algorithm 2 finds a solution that achieves an approximation ratio near one.

Theorem 9. *In Model 1, denote λ_1, λ_2 to be the largest and second largest eigenvalue of Σ , respectively, and assume $\lambda_1 - \lambda_2 > 0$. Let W^* be an optimal solution to SPCA-SDP. Denote n^* the number defined in (3). Then, for $l \geq 1$, suppose that one has $n \geq l \cdot n^*$, then for any number of iterations $N \geq 0$, Algorithm 2 with input (A, W^*, k, N) has an approximation ratio of at most $1 + 2/(8\sqrt{l} - 1)$ with probability at least $1 - d^{-10}$.*

5 Numerical tests

In this section, we present our numerical results. Our main objective is to evaluate the performance of Algorithm 2 on real-world datasets and compare computational performance with existing state-

of-the-art algorithms that run in *polynomial time* and have an approximation guarantee. It should be noted that, while comparisons are made, they are limited to a selected subset of existing algorithms, rather than an exhaustive review of all available methods. For further comparisons of SPCA-SDP with other algorithms, readers are directed to the recent study in [13]. We conducted tests on several real-world datasets, with the dimension of matrix A ranging from 79 to 2000. For most available SDP solvers, including Mosek [2] and SCS [36], face weak scalability, making it hard for them to handle semidefinite programs with dimensions exceeding 1000. As a result, we use CGAL [45] to obtain approximation solutions to SPCA-SDP. It is worth noting that, in Algorithm 1, we simply take the set T (on line 8) with $|T| = k - |S|$ to be the index set in $[d] \setminus S$ that yields largest W_{ii} 's (with ties broken arbitrarily).

Introduction to CGAL. The conditional gradient augmented Lagrangian framework (CGAL) [45] is an iterative algorithm that (approximately) solves the following problem:

$$f(x^*) := \min f(x) \quad \text{s.t. } x \in \mathcal{X}, \quad Cx \in \mathcal{K},$$

where f is a convex and L -smooth function, C is a linear mapping, \mathcal{X} is a convex compact set and \mathcal{K} is a convex set. In the m -th iteration, CGAL is guaranteed to find x_m such that $|f(x_m) - f(x^*)| \leq \mathcal{O}(m^{-1/2})$ and $\text{dist}(Cx_m, \mathcal{K}) \leq \mathcal{O}(m^{-1/2})$. In the tests, number of iterations in CGAL is set to 100 and the parameter λ_0 set to 1, and we initialize x_0 to be the zero matrix—which guarantees that $\text{rank}(x_m) \leq m$. We find that this algorithm could be efficiently implemented on GPU.

Hardware. We conducted all tests on a personal computer with 8 Cores i7-9700K 3.60GHz CPU, 64 GB of memory, and NVIDIA GEFORCE RTX 2080 SUPER with 8 GB of GPU memory.

Baselines. We compare polynomial-time algorithms studied in [37, 12, 32, 4]. It is worth noting that Chan's algorithm studied in [12] finds a $\min\{\sqrt{k}, d^{1/3}\}$ -approximate solution to SPCA. To the best of our knowledge, this is the best known approximation ratio that can be obtained in polynomial time for general SPCA. We also compare the performance of Algorithm 2, among the Greedy algorithm and the Local Search algorithm studied in [32], and the Low-Rank method studied in [37]. The Greedy algorithm and the Local Search algorithm both find k -approximate solutions in polynomial time, while the Low-Rank method [37] finds a solution with approximation ratio depending on the decay of the eigenvalues of the input matrix A . For computational efficiency, we apply the Low-Rank method with the rank-2 approximation to A .

We also compare with the Branch-and-Bound (BB) algorithm from [4] and MSPCA algorithm from [21], while the latter finds SPCA both a lower bound (LB) using a heuristic and an upper bound (UB) using MILP. Although BB and MSPCA frequently find good solutions within our time limit, both algorithms have worst-case running times that could grow exponentially with k , so we treat their results as supplementary to the core comparison among polynomial-time methods. BB has no approximation guarantee, and MSPCA, while returning an upper bound within a constant factor of the optimum, still provides no polynomial runtime bound. By contrast, Greedy, Local Search, Low-Rank, and Algorithm 2 combine provable approximation ratios with guaranteed polynomial complexity, making them the efficient choice for large-scale instances (see Table 1).

Summary of results. In Figure 1, we report the following *Chan-normalized Gap* for the five algorithms, and use Chan's Algorithm as a baseline:

$$\text{Chan-normalized Gap} := \frac{\text{Obj}_{\text{alg}} - \text{Obj}_{\text{Chan}}}{\text{Obj}_{\text{Chan}}} \times 100\%,$$

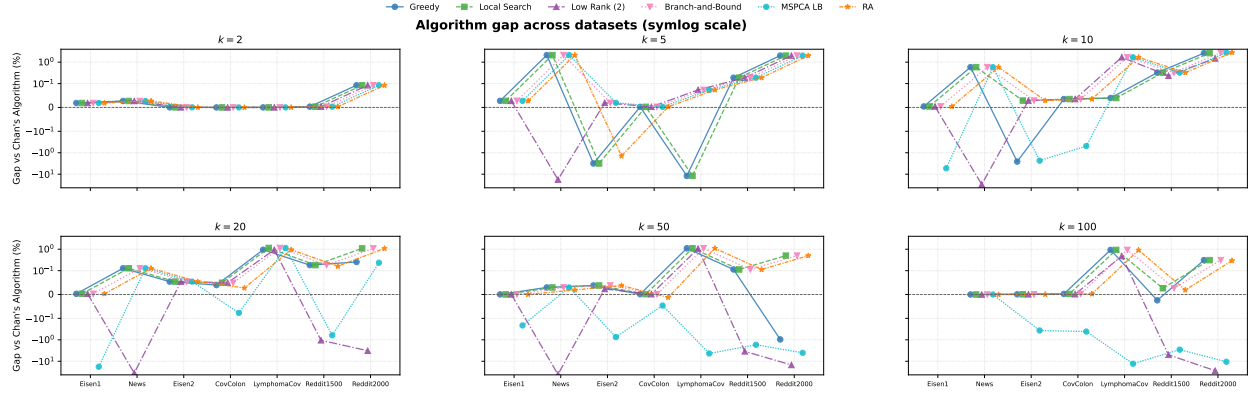


Figure 1: **Chan-normalized gaps (higher = better)**. Each panel fixes the sparsity level k and plots the Chan-normalized gaps of the six algorithms across the seven benchmark datasets, ordered from the smallest to the largest dimension (left to right). Our Randomized Algorithm achieves the best objective on 31 of the 41 instances (75%) and never falls below Chan by more than 1.5%. Note that we do not report the result for $k = 100$ on the Eisen1 dataset as its dimension is smaller than 100.

where Obj_{Chan} is the SPCA objective value found by Chan’s algorithm, and Obj_{alg} is that of the algorithm under test. Across 41 benchmark instances, and up to a tolerance of 10^{-3} in objective values, Algorithm 2 (RA) attains the best objective in 31 cases and matches or exceeds the competitors as follows:

- Greedy algorithm: 85% of instances (20% strictly better);
- Local Search algorithm: 80% (10% strictly better);
- Low-Rank method: 90% (39% strictly better);
- Chan’s algorithm: 95% (78% strictly better);
- BB: 75% (2% strictly better);
- MSPCA LB: 90% (44% strictly better).

Relative to Chan’s method, RA shows an average gap of 0.34% (max 2.80%, min -1.42%). The average Chan-normalized gaps for the Greedy algorithm, the Local Search algorithm, the Low-Rank method, BB, and MSPCA LB are -0.16%, -0.03%, -4.16%, 0.38%, and -2.43%, respectively. Note that RA obtains the highest average Chan-normalized gap among all polynomial-time algorithms. In six instances (14% of all instances) RA gains over 1% compared to Chan’s Algorithm. We also notice that, although the gaps for Greedy, Local Search, and RA shown in Figure 1 are oftentimes close to each other, RA is able to find better solutions when they fail. For example, for the instance $k = 5$ on the LymphomaCov dataset, both Greedy algorithm and Local Search algorithm find solutions with gaps around -11.97%, yet RA finds a solution with a gap 0.07%. Although BB often attains equal or better objective values compared to all four polynomial-time methods, its Chan-normalized gap exceeds that of RA by only 0.04% on average and at most 1.43%.

In Figure 2, we report the runtimes of different algorithms. It highlights that RA maintains these accuracy gains at practical speeds: the median runtime is merely 2.57 seconds, and maximum runtime is 11.95 seconds. It should be noted that the sampling of $N = 3000$ solutions only takes

less than 3.5 seconds for 75% of the instances and the maximum sampling time among the 41 instances is 9.06 seconds. RA is approximately 312 times faster than BB on average, 1512 times faster in the best case ($k = 20$ on Eisen2 dataset). Moreover, RA is approximately 15 times faster than Low-Rank method on average, 67 times faster in the best case ($k = 100$ on LymphomaCov dataset). MSPCA’s runtime covers both its lower and upper bound computations and is included only for completeness. On all 20 instances with $k \geq 20$, RA is 2.5 times faster than the Local Search algorithm on average, and 11 times faster in the best case ($k = 100$ on Reddit1500 dataset). Although RA is in general slower than the Greedy algorithm and Chan’s algorithm, it offers an accuracy–efficiency trade-off, coupling better objectives with practical scalability for large SPCA instances, as shown in Figure 1.

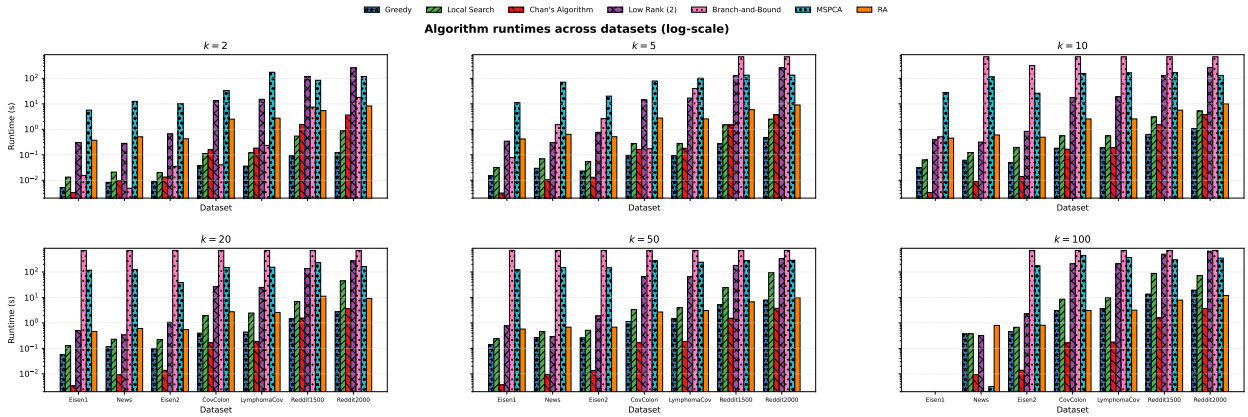


Figure 2: **Wall-clock runtimes (log scale).** The same experiments as Figure 1 but reporting runtime. RA terminates in under 10 seconds on 90% of instances. It is roughly 312 times faster than BB and 15 times faster than the Low-Rank method, while only one order of magnitude slower than the Greedy and Chan’s algorithm. When $k \geq 20$, the runtime of RA is on average 2.5 times faster than the Local Search algorithm. We do not report the result for $k = 100$ on the Eisen1 dataset as its dimension is less than 100.

It is important to note that, across all instances the assumption (1) holds with $c_0 \leq 2.16$ on average, the 80-th percentile for c_0 is merely 2.21, while the 90-th percentile is 5.29. As a result, RA invariably achieves an $\mathcal{O}(\log d)$ -approximation.

Detailed results. Comprehensive comparisons among the methods are detailed in Table 1. We use “Obj” to denote the objective value of a solution found by a certain algorithm, “Time” to denote the runtime of an algorithm. Note that we run Algorithm 2 with $N = 3000$, and report the largest objective value among those feasible solutions found in the column “Obj” belonging to “Algorithm 2”. For reproducibility, we set the random seed to 42. In the table, c_0 stands for $\sum_{i=1}^d \sqrt{W_{ii}^*}/\sqrt{k}$, measuring how far SSR is from \sqrt{k} . The column “Total Time” stands for the runtime of CGAL + Algorithm 2. We highlight the objective values that are largest among all algorithms.

Table 1: Complete numerical results for all 41 instances. Objective values and runtimes for each algorithm are reported. The time limit for Branch-and-Bound algorithm is set to 700 seconds. In the columns belonging to “CGAL”, objective values for SPCA-SDP are reported, and c_0 stands for SSR/\sqrt{k} . In the columns belonging to “Algorithm 2”, “Time” stands for the runtime of Algorithm 2 only, while “Total Time” stands for the runtime of CGAL + Algorithm 2.

Dataset	d	k	Greedy		Local Search		Chan's		Low Rank		Branch-and-Bound		MSPCA			CGAL			Algorithm 2			
			Obj	Time	Obj	Time	Obj	Time	Obj	Time	Obj	Time	LB	UB	Time	Time	SDP Obj	c ₀	Obj	Time	Total Time	
Eisen1	79	2	7.583	0.005	7.583	0.013	7.582	0.003	7.583	0.304	7.583	0.015	7.583	7.825	5.675	0.077	7.820	1.320	7.583	0.296	0.372	
Eisen1	79	5	14.076	0.015	14.076	0.032	14.072	0.003	14.076	0.343	14.076	0.078	14.076	14.272	11.131	0.071	14.623	1.023	14.076	0.349	0.420	
Eisen1	79	10	17.335	0.031	17.335	0.063	17.335	0.003	17.335	0.399	17.335	0.508	16.415	17.399	27.938	0.073	17.712	1.006	17.335	0.380	0.453	
Eisen1	79	20	17.719	0.058	17.719	0.127	17.719	0.003	17.719	0.503	17.719	700.000	14.530	17.799	117.359	0.046	18.131	0.967	17.719	0.417	0.463	
Eisen1	79	50	18.069	0.140	18.069	0.241	18.069	0.004	18.069	0.760	18.069	700.001	18.030	18.082	121.533	0.044	18.131	0.612	18.069	0.530	0.574	
News	100	2	2750.539	0.008	2750.539	0.021	2749.795	0.010	2750.540	0.282	2750.540	0.005	2750.540	2751.281	12.496	0.091	2745.233	1.521	2750.540	0.419	0.510	
News	100	5	3557.755	0.030	3557.754	0.069	3483.899	0.010	2861.836	0.300	3557.755	1.531	3557.755	3673.218	70.845	0.094	3679.519	1.126	3557.755	0.543	0.637	
News	100	10	4549.526	0.061	4549.526	0.123	4523.123	0.009	3171.891	0.316	4549.527	700.000	4549.527	4727.807	114.517	0.090	4756.311	1.043	4549.527	0.511	0.601	
News	100	20	5696.468	0.116	5696.469	0.229	5689.103	0.009	3674.691	0.336	5696.469	700.000	5696.469	5935.193	125.960	0.085	6050.354	1.011	5696.469	0.517	0.602	
News	100	50	7017.849	0.266	7017.850	0.457	7015.768	0.010	4126.741	0.290	7017.851	700.000	7017.851	7147.107	148.708	0.095	7334.629	1.000	7017.103	0.587	0.682	
News	100	100	7367.672	0.370	7367.672	0.373	7367.672	0.009	7367.672	0.316	7367.667	0.000	7367.672	7367.672	0.003	0.049	7367.672	0.755	7367.672	0.749	0.799	
Eisen2	118	2	3.976	0.009	3.976	0.020	3.976	0.013	3.976	0.655	3.976	0.034	3.976	3.989	10.164	0.107	4.167	2.103	3.976	0.320	0.427	
Eisen2	118	5	6.425	0.023	6.425	0.054	6.635	0.013	6.636	0.763	6.636	2.622	6.636	6.824	20.064	0.109	7.117	1.892	6.541	0.404	0.512	
Eisen2	118	10	11.412	0.048	11.718	0.196	11.715	0.014	11.718	0.835	11.718	315.274	11.441	11.844	26.214	0.108	11.970	1.432	11.718	0.385	0.492	
Eisen2	118	20	19.323	0.100	19.323	0.220	19.312	0.014	19.323	1.058	19.323	700.000	19.323	19.597	38.332	0.106	19.559	1.155	19.323	0.439	0.544	
Eisen2	118	50	26.035	0.257	26.035	0.515	26.025	0.014	26.031	1.883	26.035	700.000	25.831	26.280	145.161	0.109	27.083	1.003	26.035	0.575	0.684	
Eisen2	118	100	27.573	0.451	27.573	0.674	27.573	0.014	27.573	2.250	27.573	700.000	27.573	27.471	27.597	172.536	0.060	27.679	0.821	27.573	0.749	0.810
CovColon	500	2	715.395	0.038	715.395	0.113	715.395	0.160	715.395	13.481	715.395	0.040	715.395	817.226	33.006	1.955	4628.146	13.003	715.395	0.553	2.508	
CovColon	500	5	1646.454	0.096	1646.454	0.277	1646.412	0.163	1646.454	14.172	1646.454	0.172	1646.454	1664.632	78.784	2.132	5110.411	7.487	1646.454	0.639	2.771	
CovColon	500	10	2641.229	0.181	2641.229	0.557	2640.302	0.166	2641.229	17.591	2641.229	700.000	2627.404	2735.330	156.236	1.878	5819.470	5.374	2641.229	0.667	2.545	
CovColon	500	20	4255.287	0.398	4255.694	1.962	4253.598	0.166	4255.694	26.237	4255.694	700.000	4250.320	4420.541	149.264	2.052	7291.615	3.502	4254.765	0.693	2.745	
CovColon	500	50	7977.493	1.138	7977.493	3.342	7977.381	0.166	7977.493	65.019	7977.493	700.000	7973.697	8232.498	273.509	1.881	12175.880	1.889	7976.408	0.803	2.683	
CovColon	500	100	12307.385	3.010	12307.385	8.528	12307.080	0.163	12307.228	208.050	12307.385	700.003	12256.380	12511.080	446.110	1.957	16957.169	1.437	12307.385	1.125	3.081	
LymphomaCov	500	2	2064.868	0.036	2064.868	0.119	2064.864	0.184	2064.868	15.086	2064.868	0.233	2064.868	2652.215	173.575	2.119	3223.160	10.030	2064.868	0.625	2.744	
LymphomaCov	500	5	3782.621	0.094	3782.621	0.279	4297.340	0.180	4300.497	16.836	4300.497	40.169	4300.497	4375.991	101.530	1.831	5080.984	4.933	4300.497	0.734	2.565	
LymphomaCov	500	10	5911.412	0.189	5911.412	0.556	5909.077	0.191	6008.741	19.093	6008.741	700.000	6008.741	6857.551	163.512	1.797	6893.303	3.311	6008.317	0.769	2.566	
LymphomaCov	500	20	9063.961	0.439	9082.158	2.449	8979.248	0.188	9063.961	24.743	9082.158	700.001	9082.158	9916.811	153.780	1.811	10077.055	2.276	9063.960	0.770	2.580	
LymphomaCov	500	50	14546.930	1.471	14546.931	3.997	14388.111	0.186	14541.948	64.599	14546.931	700.002	13763.608	15338.658	241.648	2.139	15541.962	1.389	14546.931	0.916	3.055	
LymphomaCov	500	100	19339.870	3.696	19339.870	9.875	19162.191	0.178	19253.991	210.344	19339.870	700.000	16668.065	19260.237	370.315	1.983	20941.087	1.129	19336.097	1.188	3.171	
Reddit1500	1500	2	920.074	0.091	920.074	0.543	920.044	1.552	920.074	118.997	920.074	7.457	920.074	942.504	84.123	2.474	978.858	1.201	920.074	2.951	5.424	
Reddit1500	1500	5	980.974	0.269	980.974	1.499	979.129	1.478	980.974	125.956	980.974	700.010	980.974	1018.085	133.564	2.177	1080.998	1.105	980.974	3.740	5.917	
Reddit1500	1500	10	1045.743	0.631	1045.743	3.056	1042.357	1.534	1044.777	126.630	1045.743	700.002	1045.743	1077.079	167.336	2.347	1146.300	1.061	1045.743	3.310	5.657	
Reddit1500	1500	20	1105.286	1.463	1105.286	6.859	1103.282	1.552	1091.657	136.850	1105.286	700.007	1096.453	1132.024	231.820	5.545	1193.533	1.024	1105.068	5.627	11.172	
Reddit1500	1500	50	1172.655	5.057	1172.655	24.446	1171.323	1.529	1130.934	181.040	1172.655	700.012	1151.347	1171.751	280.928	2.546	1230.595	1.007	1172.655	4.187	6.734	
Reddit1500	1500	100	1200.142	13.617	1200.751	87.973	1200.435	1.586	1140.451	501.478	1200.751	700.012	1165.997	1187.112	297.662	2.345	1241.312	1.000	1200.663	5.527	7.871	
Reddit2000	2000	2	1254.755	0.121	1254.755	0.863	1253.590	3.643	1254.755	257.563	1254.755	17.952	1254.755	1353.007	118.676	2.568	1352.753	1.526	1254.755	5.671	8.239	
Reddit2000	2000	5	1397.358	0.463	1397.358	2.511	1369.780	3.753	1397.358	261.937	1397.358	700.008	1397.358	1543.256	134.227	2.903	1545.370	1.238	1397.358	6.195	9.099	
Reddit2000	2000	10	1521.308	1.073	1521.308	5.237	1482.320	3.705	1504.450	265.079	1523.823	700.012	1523.823	1731.351	130.650	2.848	1733.370	1.130	1523.823	7.130	9.978	
Reddit2000	2000	20	1670.471	2.738	1684.394	44.551	1666.240	3.617	1612.458	271.172	1684.395	700.012	1670.153	1961.127	164.186	2.723	2026.850	1.076	1684.394	6.459	9.182	
Reddit2000	2000	50	2289.037	7.926	2322.820	94.621	2311.241	3.751	1967.200	331.002	2322.821	700.007	2218.043	2315.127	288.524	2.831	2502.577	1.016	2322.820	6.892	9.723	
Reddit2000	2000	100	2544.370	19.426	2544.370	72.566	2536.516	3.685	1841.806	654.783	2544.371	700.007	2269.553	2338.926	349.681	2.898	2600.108	1.002	2543.924	9.057	11.955	
Average			3230.839	1.601	3232.479	9.273	3228.698	0.820	3043.605	96.081	3247.551	453.322	3150.170	3373.851	143.690	1.443	4011.721	2.169	3246.916	2.058	3.501	

6 Proofs in Section 3

In this section, we present the proofs that we owe in Section 3.

6.1 Proofs in Section 3.1

In this section, we prove Theorems 1 and 2. To do this, we need to introduce several new notation and random events.

Firstly, we show that Algorithm 1 produces a k -sparse vector with a high probability.

Proposition 10. *Let S be the set in Algorithm 1. Define a random event*

$$\mathcal{A} := \{|S| \leq k\}. \quad (5)$$

Then, \mathcal{A} holds true with probability at least $1 - \exp\{-ck\}$ for some absolute constant $c > 0$.

The proof of this property relies on the well-known multiplicative Chernoff bound:

Lemma 11 ([34], Theorem 4.4 and the remark after Corollary 4.6). *Let $X = \sum_{i=1}^d X_i$, where X_i 's are independent Bernoulli (i.e., 0-1) random variables. Let L_u be a number such that $L_u \geq \mathbb{E}X$. Then, for any $\delta > 0$, we have*

$$\mathbb{P}(X \geq (1 + \delta)L_u) \leq \left(\frac{e^\delta}{(1 + \delta)^{1+\delta}} \right)^{L_u}.$$

Proof of Theorem 10. We use Theorem 11 to prove this statement. It is equivalent to showing that $\sum_{i=1}^d \epsilon_i \leq k$ with probability at least $1 - \exp\{-ck\}$ for some $c > 0$, where ϵ_i 's are the Bernoulli random variables in Algorithm 1. Define $L_u := 3/4 \cdot k$, it is clear that $\mathbb{E} \sum_{i=1}^d \epsilon_i = \sum_{i=1}^d p_i \leq L_u$. By Theorem 11, we pick $\delta := 1/3$, and obtain the desired result with $c = -1/4 - \log(3/4) > 0.037$. \square

Now, we are ready to prove Theorem 1.

Proof of Theorem 1. Define $i^* := \arg \max_{i \in [d]} A_{ii}$, and it suffices to show that $z^\top A z \geq A_{i^* i^*} = \|A\|_\infty$ with high probability. Indeed, by Hölder's inequality, for any feasible solution W to SPCA-SDP, we have $\text{tr}(AW) \leq \|A\|_\infty \cdot \|W\|_1 \leq k \|A\|_\infty = k A_{i^* i^*}$, where the last equality follows from the fact that for any $i \neq j$, one have $A_{ij}^2 \leq A_{ii} A_{jj} \leq \max\{A_{ii}, A_{jj}\}^2$ due to $A \succeq 0$.

It is clear that the probability of the index i^* not being chosen in the support of a solution z_i obtained at the i -th iteration of Algorithm 2 is exactly $\mathbb{P}(\{i^* \text{ is not chosen in } z_i\}) = 1 - p_{i^*}$. Therefore, the probability that the support of at least one feasible solution contains i^* is given by

$$\begin{aligned} & 1 - \mathbb{P} \left(\bigcap_{i=1}^N (\{i^* \text{ is not chosen in } z_i\} \cup \{z_i \text{ is not feasible}\}) \right) \geq 1 - (1 - p_{i^*})^N - (\exp\{-ck\})^N \\ & \geq 1 - \exp\{-N p_{i^*}\} - \exp\{-ckN\} \geq 1 - \exp \left\{ -N \cdot \frac{k A_{i^* i^*}}{12 \text{tr}(A)} \right\} - \exp\{-ckN\} \\ & \geq 1 - \exp \left\{ -N \cdot \frac{k}{12d} \right\} - \exp\{-ckN\}, \end{aligned}$$

where the first inequality follows from Theorem 10 with the same $c > 0$, and at the last equality we use the fact that $d A_{i^* i^*} \geq \text{tr}(A)$. \square

To prove Theorem 2, we need an additional useful probabilistic property of the uniform random vector g that we will be used in the proof.

Proposition 12. Let $g \in \mathbb{R}^d$ be a random vector such that $g_i \stackrel{i.i.d.}{\sim} \text{Uniform}(-\sqrt{3}, \sqrt{3})$. Assume a matrix $W \succeq 0$, and denote $U := \sqrt{W}$, and let $U = (u_1, u_2, \dots, u_d)$. Define the random event as follows:

$$\mathcal{B} := \left\{ \max_{i \in [d], \|u_i\|_2 > 0} \frac{|u_i^\top g|^2}{\|u_i\|_2^2} \leq C \log d \right\} \quad (6)$$

Then, \mathcal{B} holds true for some absolute constant $C > 0$, with probability at least $1 - 2d^{-3}$.

Proof of Theorem 12. WLOG we assume that $u_i \neq 0_d$ for every $i \in [d]$. Since each g_i is a bounded random variable, we see that $g_i \sim \mathcal{SG}(3)$, i.e., $\mathbb{E} \exp\{tg_i\} \leq \exp\{3t^2/2\}$. Moreover, as each g_i has i.i.d. entries, it is clear that $u_i^\top g \sim \mathcal{SG}(3\|u_i\|_2^2)$, and hence by standard Chernoff bound (see, e.g., Section 4.2 in [34]), for an arbitrary $s > 0$, $\mathbb{P}(|u_i^\top g| > s) \leq 2 \exp\{-s^2/(6\|u_i\|_2^2)\}$. By union bound, for any $t > 0$, we obtain that

$$\mathbb{P}\left(\max_{i \in [d]} \frac{|u_i^\top g|}{\|u_i\|_2} > t\right) \leq \sum_{i=1}^d \mathbb{P}\left(\frac{|u_i^\top g|}{\|u_i\|_2} > t\right) \leq \sum_{i=1}^d 2 \exp\left\{-\frac{t^2}{6}\right\} = 2d \exp\left\{-\frac{t^2}{6}\right\}.$$

Setting $t := 2\sqrt{6}\sqrt{\log d}$ concludes the proof. \square

Now, we are ready to give a formal statement of Theorem 2:

Theorem 13. Let the notation be the same as in Theorem 2, but only assuming that $A \in \mathbb{R}^{d \times d}$ is symmetric with $\|A\|_2 = 1$. Denote random events \mathcal{A} and \mathcal{B} as defined in (5) and (6), respectively, and denote $c > 0$ and $C > 0$ the absolute constants in Theorem 10 and Theorem 12, respectively.

1. Suppose that the input matrix A has non-negative diagonal entries, then one has

$$C \log d \left[1 + \frac{9 \left(\sum_{i=1}^d \sqrt{W_{ii}^*} \right)^2}{4k} \right] \mathbb{E} \left[z^\top A z | \mathcal{A} \cap \mathcal{B} \right] \geq \left[1 - \mathcal{O}\left(\frac{1}{d}\right) \right] (x^*)^\top A x^* - \epsilon - e^{-ck + 2 \log(\frac{2d}{k})}.$$

2. Suppose, in addition, that the input matrix A is positive semidefinite, and that $ck \geq 3 \log(d/k) + \log \log d$. Then,

$$C \log d \left[1 + \frac{9 \left(\sum_{i=1}^d \sqrt{W_{ii}^*} \right)^2}{4k} \right] \mathbb{E} \left[z^\top A z | \mathcal{A} \cap \mathcal{B} \right] \geq \left[1 - \mathcal{O}\left(\frac{1}{\log d}\right) \right] (x^*)^\top A x^* - \epsilon.$$

It is clear that Theorem 13 indeed implies Theorem 2, by setting $\mathcal{R} := \mathcal{A} \cap \mathcal{B}$, and it is clear that the probability that \mathcal{R} occurs is lower bounded by $1 - \exp\{-ck\} - 2d^{-3}$ by Theorems 10 and 12.

We are now ready to prove Theorem 13.

Proof of Theorem 13. In the proof, denote by $\sqrt{W^*} = (u_1, u_2, \dots, u_d)$. We first point out a fact regarding Algorithm 1: After executing line 6, i.e., setting the set S to be the set $\{i \in [d] : \epsilon_i = 1\}$, if one draws a random vector $g \in \mathbb{R}^d$ such that its entries are all i.i.d. Uniform in $[-\sqrt{3}, \sqrt{3}]$, and defines a random vector $x \in \mathbb{R}^d$ such that $x_i = 0$ for $i \in S^c$, and $x_i = u_i^\top g / p_i$ for $i \in S$, then one can see that $z^\top A z \geq x^\top A x / \|x\|_2^2$. Indeed, this is implied by the fact that $\text{Supp}(x) \subseteq \text{Supp}(z)$, and z is chosen to the vector with larger SPCA objective on line 9.

The ideas behind the rest of the proof are as follows: The expected objective value $x^\top Ax$ is greater or equal to $\text{tr}(AW^*)$. This, coupled with the facts that $z^\top Az \geq x^\top Ax / \|x\|_2^2$, $\text{tr}(AW^*) \geq (x^*)^\top Ax^* - \epsilon$, and upper bound of $\text{tr}(AW^*)$, lead to approximation guarantees.

Expected value of $x^\top Ax$. Assuming that $p_i > 0$ for all $i \in [d]$. By definition,

$$x^\top Ax = \sum_{i,j=1}^d a_{ij} x_i x_j = \sum_{i,j=1}^d a_{ij} \cdot \left(\frac{u_i^\top g}{p_i} \cdot \epsilon_i \right) \cdot \left(\frac{u_j^\top g}{p_j} \cdot \epsilon_j \right).$$

For $i, j \in [d]$ and $i \neq j$, it holds that $\mathbb{E} x_i x_j = \mathbb{E}(u_i^\top g)(u_j^\top g) = u_i^\top (\mathbb{E} g g^\top) u_j = u_i^\top I_d u_j = u_i^\top u_j$, and for $i = j \in [d]$, we have that $\mathbb{E} x_i^2 = \mathbb{E}(u_i^\top g)^2 / p_i = u_i^\top (\mathbb{E} g g^\top) u_i / p_i = \|u_i\|_2^2 / p_i$. Since $U = \sqrt{W}$, we have that $U^2 = U^\top U = W$, and hence $W_{ij} = u_i^\top u_j$. Combining all above facts, we obtain that

$$\mathbb{E} x^\top Ax = \sum_{i=1}^d \frac{a_{ii}}{p_i} \|u_i\|_2^2 + \sum_{1 \leq i \neq j \leq d} a_{ij} u_i^\top u_j = \text{tr}(AW) + \sum_{i=1}^d \left(\frac{1}{p_i} - 1 \right) a_{ii} \|u_i\|_2^2 \geq \text{tr}(AW^*).$$

In the case where there exist some $p_i = \min\{1, 2/3 \cdot k \|u_i\|_2 / \sum_{j=1}^d \|u_j\|_2 + 1/12 \cdot k A_{ii} / \text{tr}(A)\} = 0$, it is clear that $x_i = 0$ and $W_{ii} = \|u_i\|_2^2 = 0$. $W \succeq 0$ implies that $W_{ij} = W_{ji} = 0$ for all $j \in [d]$, and thus $\mathbb{E} x_i x_j = 0 = W_{ij}$, and thus $\mathbb{E} x^\top Ax \geq \text{tr}(AW^*)$ still holds.

Upper bound of $\text{tr}(AW^*)$. By law of total expectation, we obtain that

$$\begin{aligned} \mathbb{E} x^\top Ax &= \mathbb{P}(\mathcal{A}) \cdot \mathbb{E} [x^\top Ax | \mathcal{A}] + \mathbb{P}(\mathcal{A}^c) \cdot \mathbb{E} [x^\top Ax | \mathcal{A}^c] \\ &\leq \mathbb{P}(\mathcal{A}) \cdot \mathbb{E} [x^\top Ax | \mathcal{A}] + \exp\{-ck\} \cdot \|A\|_2 \cdot \mathbb{E} [x^\top x | \mathcal{A}^c] \\ &= \mathbb{P}(\mathcal{A}) \cdot \mathbb{E} [x^\top Ax | \mathcal{A}] + \exp\{-ck\} \cdot \mathbb{E} [x^\top x | \mathcal{A}^c] \end{aligned}$$

It suffices to further upper bound $\mathbb{P}(\mathcal{A}) \cdot \mathbb{E} [x^\top x | \mathcal{A}^c]$. Again by law of total expectation, one has

$$\mathbb{P}(\mathcal{A}) \cdot \mathbb{E} [x^\top Ax | \mathcal{A}] = \mathbb{P}(\mathcal{A} \cap \mathcal{B}) \cdot \mathbb{E} [x^\top Ax | \mathcal{A} \cap \mathcal{B}] + \mathbb{P}(\mathcal{A} \cap \mathcal{B}^c) \cdot \mathbb{E} [x^\top Ax | \mathcal{A} \cap \mathcal{B}^c] \quad (7)$$

We upper bound $\|x\|_2^2$ conditioned on $\mathcal{A} \cap \mathcal{B}$ first. Pick any $x \in \mathcal{A}$, define $R := \text{Supp}(x)$ and $T := \{i \in R : p_i = 1\}$. Notice that $\sqrt{W_{ii}^*} = \|u_i\|_2$ and $p_i \geq 2/3 \cdot k \|u_i\|_2 / \sum_{j=1}^d \|u_j\|_2$, and thus

$$\begin{aligned} \|x\|_2^2 &= \sum_{i \in T} (u_i^\top g)^2 + \sum_{i \in R \setminus T} \frac{(u_i^\top g)^2}{p_i^2} \leq \sum_{i \in T} (u_i^\top g)^2 + \frac{9}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \sum_{i \in R \setminus T} \frac{(u_i^\top g)^2}{\|u_i\|_2^2} \\ &\stackrel{\mathcal{B}}{\leq} \sum_{i \in S} (C \log d) \cdot \|u_i\|_2^2 + \frac{9}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \cdot k \cdot C \log d \leq C \log d \left[1 + \frac{9}{4k} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \right]. \end{aligned}$$

Define $\bar{x} := x / \|x\|_2$. Hence, for the first term in (7), it is clear that

$$\mathbb{E} [x^\top Ax | \mathcal{A} \cap \mathcal{B}] = \mathbb{E} [\|x\|_2^2 \bar{x}^\top A \bar{x} | \mathcal{A} \cap \mathcal{B}] \leq C \log d \left(1 + \frac{9 \left(\sum_{i=1}^d \|u_i\|_2 \right)^2}{4k} \right) \mathbb{E} [\bar{x}^\top A \bar{x} | \mathcal{A} \cap \mathcal{B}].$$

Next, we upper bound the second term in (7). By Theorem 12, it is clear that $\mathbb{P}(\mathcal{B}^c) \leq 2d^{-3}$, thus

$$\mathbb{P}(\mathcal{A} \cap \mathcal{B}^c) \mathbb{E} [x^\top Ax | \mathcal{A} \cap \mathcal{B}^c] \leq \frac{2}{d^3} \mathbb{E} [x^\top Ax | \mathcal{A} \cap \mathcal{B}^c] \leq \frac{2}{d^3} [(x^*)^\top Ax^*] \mathbb{E} [\|x\|_2^2 | \mathcal{A} \cap \mathcal{B}^c].$$

Then, we give an upper bound for $\mathbb{E} [\|x\|_2^2 | \mathcal{A} \cap \mathcal{B}^c]$. By writing down $\|x\|_2^2$ explicitly, and by the fact that $(u_i^\top g)^2 \leq \|u_i\|_2^2 \|g\|_2^2$, we observe that

$$\mathbb{E} [\|x\|_2^2 | \mathcal{A} \cap \mathcal{B}^c] \leq \mathbb{E} \left[\sum_{i \in T} (u_i^\top g)^2 + \frac{9}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \cdot \sum_{i \in R \setminus T} \frac{(u_i^\top g)^2}{\|u_i\|_2^2} \middle| \mathcal{A} \cap \mathcal{B}^c \right]$$

$$\begin{aligned}
&\leq \mathbb{E} \left[\sum_{i \in T} \|u_i\|_2^2 \|g\|_2^2 + \frac{9}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \cdot \sum_{i \in R \setminus T} \frac{\|u_i\|_2^2 \|g\|_2^2}{\|u_i\|_2^2} \middle| \mathcal{A} \cap \mathcal{B}^c \right] \\
&\leq \mathbb{E} \left[\|g\|_2^2 + \frac{9}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \cdot \sum_{i \in R \setminus T} \|g\|_2^2 \middle| \mathcal{A} \cap \mathcal{B}^c \right] \leq 3d + \frac{27d}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2,
\end{aligned}$$

where the last inequality follows from $g_i \sim \text{Uniform}(-\sqrt{3}, \sqrt{3})$ and hence $\|g\|_2^2 \leq 3d$. Finally, combining all bounds above, we obtain that $\mathbb{P}(\mathcal{A}) \cdot \mathbb{E}[x^\top A x | \mathcal{A}]$ is upper bounded by

$$C \log d \mathbb{P}(\mathcal{A} \cap \mathcal{B}) \left(1 + \frac{9(\sum_{i=1}^d \|u_i\|_2)^2}{4k} \right) \mathbb{E}[\bar{x}^\top A \bar{x} | \mathcal{A} \cap \mathcal{B}] + (x^*)^\top A x^* \left(\frac{6}{d^2} + \frac{27(\sum_{i=1}^d \|u_i\|_2)^2}{2k^2 d^2} \right).$$

Hence, we see that $\text{tr}(A W^*)$ is upper bounded by the sum of $\exp\{-ck\} \mathbb{E}[x^\top x | \mathcal{A}^c]$ and the above quantity. We are now ready to show the two parts in the statement of Theorem 13.

(Proof for part 1) We write $\delta := \exp\{-ck + 2 \log 2d/k\}$. Direct calculation shows that

$$\begin{aligned}
\mathbb{E}[x^\top x | \mathcal{A}^c] &= \mathbb{E} \left[\sum_{i: p_i > 0} \frac{(u_i^\top g)^2}{p_i^2} \epsilon_i \middle| \mathcal{A}^c \right] \leq \mathbb{E} \left[\sum_{i: p_i > 0} \frac{(u_i^\top g)^2}{p_i^2} \middle| \mathcal{A}^c \right] = \sum_{i: p_i > 0} \frac{\mathbb{E}(u_i^\top g)^2}{p_i^2} \\
&\leq \sum_{i: p_i = 1} \frac{\mathbb{E}(u_i^\top g)^2}{p_i^2} + \sum_{i: 0 < p_i < 1} \frac{\mathbb{E}(u_i^\top g)^2}{p_i^2} \leq 1 + \frac{9d}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2.
\end{aligned}$$

By the definition of δ , one obtains that $\exp\{-ck\} \mathbb{E}[x^\top x | \mathcal{A}^c] \leq \delta$.

(Proof for part 2) For this part, we assume that $A \succeq 0$. In this special case, we claim that $1 = \|A\|_2 \leq \frac{d}{k} \cdot (x^*)^\top A x^*$. This inequality holds true for the following reasoning:

- first, there exists a $(d-1) \times (d-1)$ principal submatrix \tilde{A} of A such that $\|A\|_2 \leq d/(d-1) \cdot \|\tilde{A}\|_2$ (for a reference, see, e.g., the arguments on page 189 in [25]);
- then, using the above fact repeatedly for the existence of a principal submatrix of size $d-2, d-3, \dots, k$, one can obtain a principal submatrix \hat{A} of size k such that $\|A\|_2 \leq d/k \cdot \|\hat{A}\|_2$.

Combining the above inequality and the inequality in the proof for part 1, one obtains that

$$\begin{aligned}
\exp\{-ck\} \mathbb{E}[x^\top x | \mathcal{A}^c] &= \exp\{-ck\} \mathbb{E}[x^\top x | \mathcal{A}^c] \cdot \|A\|_2 \\
&\leq \exp\{-ck\} \cdot \left[1 + \frac{9d}{4k^2} \left(\sum_{i=1}^d \|u_i\|_2 \right)^2 \right] \cdot \frac{d}{k} \cdot (x^*)^\top A x^* \leq \mathcal{O} \left(\frac{1}{\log d} \right) \cdot (x^*)^\top A x^*,
\end{aligned}$$

where the last inequality comes from the assumption that $ck \geq 3 \log d/k + \log \log d$. \square

6.2 Proofs in Section 3.3

In this section, we prove Theorem 6 and Theorem 7 in Section 3.3. To prove them, we need several technical lemmas. We first introduce the core lemma, Theorem 14, which is derived directly from the well-known KKT conditions [29].

Lemma 14. $W^* = w^*(w^*)^\top$ is an optimal solution to SPCA-SDP if the following conditions hold:

B1 (Primal feasibility) $\|w^*\|_1 \leq \sqrt{k}$ and $\|w^*\|_2 = 1$;

B2 (Dual feasibility) $\mu^* \geq 0$, $\lambda^* \in \mathbb{R}$, $Z^* \in [-1, 1]^{d \times d}$ such that $Z_{ij}^* = \text{sign}(w_i^*) \cdot \text{sign}(w_j^*)$ if $w_i^* w_j^* \neq 0$, and $\lambda^* I_d \succeq A - \mu^* Z^*$;

B3 (Complementary slackness) $\mu^*(\|w^*\|_1 - \sqrt{k}) = 0$, $(\lambda^*I_d - A + \mu^*Z^*)w^* = 0$.

Moreover, if $\text{rank}(\lambda^*I_d - A + \mu^*U^*) = d - 1$, then W^* is the unique optimal solution to SPCA-SDP.

Proof. It is clear that the dual problem to SPCA-SDP is given by

$$\min_{\mu, \lambda, S, U} k\mu + \lambda \quad \text{s.t. } \mu \geq 0, S \succeq 0, U = A + S - \lambda I_d, \|U\|_\infty \leq \mu,$$

and hence conditions B1, B2, and B3 are clear from KKT conditions [29]. Finally, if $\text{rank}(\lambda^*I_d - A + \mu^*U^*) = d - 1$, we know that for any optimal solution W_0 to SPCA-SDP, it must hold that $\text{rank}(W_0) = d - \text{rank}(\lambda^*I_d - A + \mu^*U^*) = 1$ since $\text{tr}(W_0(\lambda^*I_d - A + \mu^*U^*)) = 0$. Due to the fact that $(\lambda^*I_d - A + \mu^*U^*)w^* = 0$, we see that W_0 must be equal to $w^*(w^*)^\top$. \square

We are now ready to prove Theorem 6.

Proof of Theorem 6. WLOG, we assume that $\|u\|_2 = 1$, as a scaling of A by a non-negative constant would not change its optimal solution to SPCA-SDP. Furthermore, we assume WLOG that $\lambda = 0$, as adding a scaling of an identity matrix to A would not change its optimal solution to SPCA-SDP either. We complete the proof by utilizing Theorem 14.

(Primal feasibility). For simplicity, we define $t_0 := \min_{i \in T} |u_i|$, with $T = \text{Supp}(u)$. Since $\|u\|_1 > \sqrt{k}$, it is clear that $|T| \geq \|u\|_1^2 > k$. We define a unit vector $w(t) := (u - t \text{sign}(u)) / \|u - t \text{sign}(u)\|_2 \in \mathbb{R}^d$ with $t \in [0, t_0]$. We claim that $\|w(t_0)\|_1 < \sqrt{k}$. Indeed, the claim is equivalent to the quadratic inequality $|T|(|T| - k)t_0^2 - 2\|u\|_1(|T| - k)t_0 + (\|u\|_1^2 - k) < 0$, which is then implied by (2). Therefore, by the Intermediate Value Theorem, there exists $t^* \in (0, t_0)$ such that $\|w(t^*)\|_1 = \sqrt{k}$.

We thus define $w^* = w(t^*)$, it is clear that $\|w^*\|_2 = 1$, $\|w^*\|_1 = \sqrt{k}$, and $\text{Supp}(w^*) = T$.

(Dual feasibility). By the definition of w^* , we see that $\text{sign}(w^*) = \text{sign}(u)$, and we obtain that

$$u = \|u - t^* \text{sign}(u)\|_2 w^* + t^* \text{sign}(w^*) := \alpha w^* + \beta \text{sign}(w^*),$$

where $\alpha, \beta > 0$ by definition. We then define

$$\lambda^* := \|u - t^* \text{sign}(u)\|_2 (u^\top w^*) = \alpha(u^\top w^*) = \alpha(\alpha + \beta\sqrt{k}) > 0$$

$$\mu^* := \frac{t^*(u^\top w^*)}{\sqrt{k}} = \frac{\beta(u^\top w^*)}{\sqrt{k}} = \frac{\beta(\alpha + \beta\sqrt{k})}{\sqrt{k}} > 0.$$

We further define $Z^* = \text{sign}(u) \text{sign}(u)^\top$, and we show that

$$\lambda^*I_d \succeq uu^\top - \mu^*Z^* \iff \lambda^*I_d \succeq uu^\top - \mu^* \text{sign}(u) \text{sign}(u)^\top.$$

For simplicity, define $M := \lambda^*I_d - uu^\top + \mu^* \text{sign}(u) \text{sign}(u)^\top$. Since $u \in \text{Span}(w^*, \text{sign}(w^*))$, it is clear that for any non-zero vector $v \in \text{Span}(w^*, \text{sign}(w^*))^\perp$, $v^\top Mv = \lambda^* \|v\|_2^2 > 0$. Next, take any non-zero vector $v \in \text{Span}(w^*, \text{sign}(w^*))$, we also show that $v^\top Mv \geq 0$. First, we observe that

$$Mw^* = (\lambda^*I_d - uu^\top + \mu^* \text{sign}(u) \text{sign}(u)^\top)w^* = \lambda^*w^* - (u^\top w^*)u + \mu^*\sqrt{k} \text{sign}(u) = 0,$$

where the last equality follows from the fact that $u = \alpha w^* + \beta \text{sign}(w^*) = \alpha w^* + \beta \text{sign}(u)$ and how λ^* and μ^* are defined. For simplicity, define $s := \text{sign}(w^*) = \text{sign}(u)$, and we notice that

$$\begin{aligned} s^\top Ms &= s^\top (\lambda^*I_d - uu^\top + \mu^* \text{sign}(u) \text{sign}(u)^\top) s = (\lambda^* + \mu^*|T|)|T| - \|u\|_1^2 \\ &= \alpha^2 + \alpha\beta\sqrt{k} + \frac{\alpha\beta|T|}{\sqrt{k}} + \beta^2|T|^2 - (\alpha\sqrt{k} + \beta|T|)^2 = \alpha^2(|T| - k) + \frac{\alpha\beta|T|}{\sqrt{k}}(|T| - k) > 0. \end{aligned}$$

Thus, for any $v = \alpha w^* + \beta \text{sign}(w^*)$, we see that $v^\top Mv = \beta^2 \text{sign}(w^*)^\top M \text{sign}(w^*) \geq 0$.

Hence, we have shown that $M \succeq 0$, with its smallest eigenvalue being zero, and a positive second smallest eigenvalue. This implies that $\text{rank}(M) = d - 1$.

(Complementary slackness). The complementary slackness conditions follow from the fact that $\|w^*\|_1 = \sqrt{k}$ and $Mw^* = 0$. \square

Before we jump in the proof of Theorem 7, let us explain the high-level ideas. To utilize Theorem 14, the key is to construct a feasible primal solution w^* with great property. Since we

are not able to present a closed-form solution of w^* , we instead show that, such w^* has a special parameterized form $w^* = w^*(\lambda)$, where the only parameter is $\lambda \in \mathbb{R}$. We show that there must exist an interval I of λ such that for some $\lambda^* \in I$, $w^*(\lambda^*)$ satisfies primal feasibility. The interval is given in Theorem 15. Since we do not know what the exact value of w^* , or equivalently, λ^* , we additionally need A2 in Assumption 1 helps keep the sign of $w^*(\lambda)$ unchanged in that interval.

In the next lemma, we discuss the property of a special function:

Lemma 15. *Under Assumption 1, consider the vector $w(\lambda) := (A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)$, and define the function $R(\lambda) := \|w(\lambda)\|_1 / \|w(\lambda)\|_2$ for $\lambda \in (\lambda_2, \lambda_1)$. Then, there exists a $\lambda^* \in [\lambda_1/(D+1), \lambda_1) \subseteq (\lambda_2, \lambda_1)$ such that $R(\lambda^*) = \sqrt{k}$, where $D = \sqrt{\frac{4\|v_1\|_1^4 - k\|v_1\|_1^2}{k \sum_{i=2}^{|S|} \alpha_i^2}}$ as in Assumption 1. Moreover, the constant $\delta > 0$ indeed exists for A3 in Assumption 1, and we have that*

$$\frac{2\|v_1\|_1^2}{\delta} \geq \|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2 \geq \frac{(1-\gamma)\|v_1\|_1^2}{\sqrt{|S|}\lambda_1} \cdot \frac{D+1}{D}.$$

Proof. We first show that the function $R(\lambda)$ is continuous on the interval (λ_2, λ_1) . Indeed, we see that the matrix $(A_{S,S} - \lambda I_{|S|})^{-1} = \sum_{i=1}^{|S|} \frac{1}{\lambda_i - \lambda} v_i v_i^\top$ is continuous on the interval, and thus $R(\lambda)$.

To show the existence of λ^* , we use the intermediate value theorem for continuous function. First, we observe that $(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1) = \sum_{i=1}^{|S|} \frac{v_i^\top \text{sign}(v_1)}{\lambda_i - \lambda} v_i$. Since $v_1^\top \text{sign}(v_1) = \|v_1\|_1 > \sqrt{k} > 0$, we see that when $\lambda \rightarrow \lambda_1^-$, the vector is dominated by $\|v_1\|_1 / (\lambda_1 - \lambda) \cdot v_1$, and hence $R(\lambda) \rightarrow \|v_1\|_1 / \|v_1\|_2 = \|v_1\|_1 > \sqrt{k}$.

Thus, to use intermediate value theorem, it suffices to find a $\lambda_* \in (\lambda_2, \lambda_1)$ such that $R(\lambda_*) \leq \sqrt{k}$. We take $\lambda_* = \lambda_1/(D+1)$, where D is defined in Assumption 1, i.e., $D = \sqrt{\frac{4\|v_1\|_1^4 - k\|v_1\|_1^2}{k \sum_{i=2}^{|S|} \alpha_i^2}}$. From A1, it is clear that $\lambda_* \in (\lambda_2, \lambda_1)$. Along with A2 in Assumption 1, we see that

$$\begin{aligned} R(\lambda_*) &= \frac{\sum_{j=1}^{|S|} \left| \frac{\|v_1\|_1}{\lambda_1 - \lambda_*} v_{1,j} + \sum_{i=2}^{|S|} \frac{\alpha_i}{\lambda_i - \lambda_*} v_{i,j} \right|}{\sqrt{\sum_{i=1}^{|S|} \left(\frac{\alpha_i}{\lambda_i - \lambda_*} \right)^2}} = \frac{\sum_{j=1}^{|S|} \left| \|v_1\|_1 v_{1,j} + \sum_{i=2}^{|S|} \frac{\lambda_1 - \lambda_*}{\lambda_i - \lambda_*} v_{i,j} \right|}{\sqrt{\sum_{i=1}^{|S|} \alpha_i^2 \left(\frac{\lambda_1 - \lambda_*}{\lambda_i - \lambda_*} \right)^2}} \\ &\leq \frac{2\|v_1\|_1^2}{\sqrt{\sum_{i=1}^{|S|} \alpha_i^2 \left(\frac{\lambda_1 - \lambda_*}{\lambda_i - \lambda_*} \right)^2}} \leq \frac{2\|v_1\|_1^2}{\sqrt{\|v_1\|_1^2 + \sum_{i=2}^{|S|} \alpha_i^2 \left(\frac{\lambda_1 - \lambda_*}{\lambda_i - \lambda_*} \right)^2}} = \frac{2\|v_1\|_1^2}{\sqrt{\frac{4\|v_1\|_1^4}{k}}} = \sqrt{k}. \end{aligned}$$

To see the existence of $\delta > 0$ in Assumption 1, we use the previous observation that $R(\lambda)$ is a continuous function on the interval (λ_2, λ_1) , and that $R(\lambda) \rightarrow \|v_1\|_1 > \sqrt{k}$ as $\lambda \rightarrow \lambda_1^-$. Then, we give a lower bound for $\|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_2$. By Cauchy-Schwarz inequality and by A2,

$$\|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_2 \leq \|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_1 \leq \frac{2}{\lambda - \lambda^*} \|v_1\|_1^2 \leq \frac{2}{\delta} \|v_1\|_1^2$$

Finally, by Cauchy-Schwarz inequality and again by A2, we have that

$$\begin{aligned} \|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_2 &\geq \frac{1}{\sqrt{|S|}} \cdot \|(A_{S,S} - \lambda I_{|S|})^{-1} \text{sign}(v_1)\|_1 \geq \frac{(1-\gamma)\|v_1\|_1^2}{\sqrt{|S|} \cdot (\lambda_1 - \lambda^*)} \\ &\geq \frac{(1-\gamma)\|v_1\|_1^2}{\sqrt{|S|} \cdot (\lambda_1 - \lambda_*)} = \frac{(1-\gamma)\|v_1\|_1^2}{\sqrt{|S|}\lambda_1} \cdot \frac{D+1}{D}. \end{aligned}$$

□

Finally, we are ready to prove Theorem 7.

Proof of Theorem 7. We complete the proof by utilizing Theorem 14.

(Primal feasibility). We construct the vector w^* as follows: first, let S be the set in Assumption 1, and let $S^c := [d] \setminus S$. We set the entries of $w_{S^c}^*$ to be all zero, and choose $w_S^* := (A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1) / \|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2$, where λ^* is the one in Theorem 15. By Theorem 15, it is clear that $\|w^*\|_2 = \|w_S^*\|_2 = 1$, and $\|w^*\|_1 = \|w_S^*\|_1 = \sqrt{k}$.

(Dual feasibility). We first set $\mu^* := 1/\sqrt{k} \cdot \|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2 \geq 0$. Then, with a bit abuse of notation, we set λ^* to be exactly the one in Theorem 15.

For Z^* , we first make the following observation: A2 implies that the sign of w_S^* is exactly the same as v_1 , i.e., $\text{sign}(w_S^*) = \text{sign}(v_1)$. Therefore, we set $Z_{S,S}^* := \text{sign}(w_S^*) \text{sign}(w_S^*)^\top = \text{sign}(v_1) \text{sign}(v_1)^\top$. For the remaining $(i, j) \in [d] \times [d]$, with $i, j \notin S$, we set $Z_{ij}^* = A_{ij}/\mu^*$. This implies $Z_{ij}^* \in [-1, 1]$, as we can see in A3 in Assumption 1, one has

$$\max \left\{ \max_{\substack{i \in S, \\ j \in S^c}} |A_{ij}|, \max_{i, j \in S^c} |A_{ij}| \right\} \leq \frac{\delta}{2\sqrt{k} \|v_1\|_1^2} \leq \frac{1}{\sqrt{k} \|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2} = \mu^*,$$

where the last inequality is from Theorem 15. We leave the proof of $\lambda^* I_d \succeq A - \mu^* Z^* \succeq 0$ to the last part in this proof.

(Complementary Slackness). It is clear that $\mu^*(\|w^*\|_1 - \sqrt{k}) = 0$ holds as $\|w^*\|_1 = \sqrt{k}$, and hence we only need to show that $(\lambda^* I_d - A + \mu^* Z^*)w^* = 0$. An observation is that the matrix $-A + \mu^* Z^*$ have zero entries outside of the support $S \times S$, and $\text{Supp}(w^*) = S$, and thus we only need to show that $(\lambda^* I_{|S|} - A_{S,S} + \mu^* \text{sign}(w_S^*) \text{sign}(w_S^*)^\top)w_S^* = 0$. This comes from a direct calculation that $\text{sign}(w_S^*)^\top w_S^* = \|w_S^*\|_1 = \sqrt{k}$, and from the definition of w_S^* we see that

$$(A_{S,S} - \lambda^* I_{|S|})w_S^* = \frac{\text{sign}(w_S^*)}{\|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2} = \mu^* \cdot \sqrt{k} \cdot \text{sign}(w_S^*).$$

(Proof of $\lambda^* I_d \succeq A - \mu^* Z^*$). In this part, we show that $\lambda^* I_d \succeq A - \mu^* Z^*$. Since $\lambda^* \geq \lambda_2 \geq 0$, and the matrix $-A + \mu^* Z^*$ have zero entries outside of the support $S \times S$, it suffices to show that $\lambda^* I_{|S|} \succeq A_{S,S} - \mu^* \text{sign}(v_1) \text{sign}(v_1)^\top$.

Define the i -th largest eigenvalue of $\lambda^* I_{|S|} - A_{S,S} + \mu^* \text{sign}(v_1) \text{sign}(v_1)^\top$ to be ν_i , and define the i -th largest eigenvalue of $\lambda^* I_{|S|} - A_{S,S}$ to be γ_i . By the fact that $(\lambda^* I_{|S|} - A_{S,S} + \mu^* \text{sign}(w_S^*) \text{sign}(w_S^*)^\top)w_S^* = 0$, it is clear that $\nu_{|S|} = 0$. Therefore, it suffices to show that $\nu_{|S|-1} \geq 0$. By Weyl's inequality, it is clear that $|\nu_{|S|-1} - \gamma_{|S|-1}| \leq \|\mu^* \text{sign}(w_S^*) \text{sign}(w_S^*)^\top\|_2 = \mu^* \cdot k$. Since $\gamma_{|S|-1} = \lambda^* - \lambda_2 \geq 0$, by Theorem 15, and then by A1, we see that

$$\begin{aligned} \nu_{|S|-1} &\geq \gamma_{|S|-1} - \mu^* \cdot k = \lambda^* - \lambda_2 - \mu^* \cdot k \geq \frac{\lambda_1}{D+1} - \lambda_2 - \frac{\sqrt{k}}{\|(A_{S,S} - \lambda^* I_{|S|})^{-1} \text{sign}(v_1)\|_2} \\ &\geq \frac{\lambda_1}{D+1} - \lambda_2 - \frac{\sqrt{k}}{\frac{(1-\gamma)\|v_1\|_1^2}{\sqrt{|S|\lambda_1}} \cdot \frac{D+1}{D}} = \frac{\lambda_1}{D+1} \left(1 - \frac{D\sqrt{k} \cdot |S|}{(1-\gamma)\|v_1\|_1^2} \right) - \lambda_2 \geq 0 \end{aligned}$$

Finally, if the inequality in A1 in Assumption 1 is strict, then we see that $\nu_{|S|-1} > 0$, and hence the matrix $\lambda^* I_d - A + \mu^* U^*$ has rank $d - 1$. Therefore, $W^* = w^*(w^*)^\top$ is the unique optimal solution to SPCA-SDP. \square

7 Proofs in Section 4

In this section, we present the proofs of Theorems 8 and 9 in Section 4.

We first provide the proof of Theorem 8. In order to do so, we need several propositions. The first proposition characterizes how close W^* is to the “sparse spike” in a deterministic model:

Proposition 16. *Suppose the input matrix in SPCA can be written as $A = B^\top B + E$, where $B^\top B$ admits a k -sparse eigenvector v corresponding to its largest eigenvalue $\lambda_1(B^\top B)$, and $E \in \mathbb{R}^{d \times d}$ is a matrix such that $\|E\|_\infty \leq a$. Assume that $\lambda_1(B^\top B) - \lambda_2(B^\top B) > 0$, and denote W^* an optimal solution to SPCA-SDP. Then, we have*

$$\|W^* - vv^\top\|_F \leq \frac{2ak}{\lambda_1 - \lambda_2} + \sqrt{\frac{2ak}{\lambda_1 - \lambda_2}}$$

To prove Theorem 16, we utilize the curvature lemma presented in [41]. This lemma helps transform the problem of bounding the Frobenius distance of W^* and vv^\top into bounding the difference of their objective values of SPCA-SDP, which can be done at more ease.

Lemma 17 (Lemma 3.1 in [41]). *Let B be a symmetric $d \times d$ matrix and P be the projection onto the subspace spanned by the eigenvectors of B corresponding to its l largest eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_l$. If $\delta := \lambda_l - \lambda_{l+1} > 0$, then for any symmetric matrix F satisfying $0 \preceq F \preceq I_d$ and $\text{tr}(F) = l$, we have*

$$\|P - F\|_F^2 \leq \frac{2}{\delta} \text{tr}(B(P - F)).$$

Remark. In Theorem 17, suppose B admits a singular value decomposition $B = \sum_{i=1}^d \lambda_i u_i u_i^\top$, then the matrix $P = \sum_{i=1}^l u_i u_i^\top$.

Proof of Theorem 16. In the proof, we will denote $\lambda_1 := \lambda_1(B^\top B)$ and $\lambda_2 := \lambda_2(B^\top B)$, i.e., the largest and the second largest eigenvalue of $B^\top B$, respectively. By Theorem 17, we obtain that

$$\|vv^\top - W^*\|_F^2 \leq \frac{2}{\lambda_1 - \lambda_2} \text{tr}(B^\top B(vv^\top - W^*)) = \frac{2}{\lambda_1 - \lambda_2} \text{tr}((A - E)(vv^\top - W^*)).$$

Since vv^\top is feasible to problem SPCA-SDP, we have $\text{tr}(AW^*) \geq \text{tr}(Avv^\top)$. Combining this with the above inequality, we see that

$$\|vv^\top - W^*\|_F^2 \leq \frac{2}{\lambda_1 - \lambda_2} \left[-\text{tr}(E(vv^\top - W^*)) \right] \leq \frac{2\|E\|_\infty}{\lambda_1 - \lambda_2} \|vv^\top - W^*\|_1 \leq \frac{2a\|vv^\top - W^*\|_1}{\lambda_1 - \lambda_2}.$$

Let $\hat{W}_{S^c}^*$ be a matrix such that it is zero out in (S, S) block, and it coincides with the remaining entries in W^* . By Cauchy-Schwartz inequality and the fact that $\|\hat{W}_{S^c}^*\|_1 \leq k$, we obtain that

$$\|vv^\top - W^*\|_1 = \|v_S v_S^\top - W_{S,S}^*\|_1 + \|\hat{W}_{S^c}^*\|_1 \leq k \|v_S v_S^\top - W_{S,S}^*\|_F + k$$

Therefore, we see that

$$\|vv^\top - W^*\|_F^2 \leq \frac{2ak}{\lambda_1 - \lambda_2} \|v_S v_S^\top - W_{S,S}^*\|_F + \frac{2ak}{\lambda_1 - \lambda_2}.$$

We conclude the proof by noticing that, for some non-negative number $c \geq 0$, the quadratic inequality $x^2 \leq cx + c$ implies that $x \leq (c + \sqrt{c^2 + 4c})/2 \leq c + \sqrt{c}$. \square

To apply Theorem 16 to Model 1, we need the following high probability bound:

Lemma 18. In Model 1, denote λ_1, λ_2 to be the largest and second largest eigenvalue of Σ , respectively, and assume $\lambda_1 - \lambda_2 > 0$. Write

$$A = n\Sigma + (B^\top B - n\Sigma) + (M^\top M + M^\top B + B^\top M) =: n\Sigma + E. \quad (8)$$

Then,

$$\frac{1}{n} \|E\|_\infty \leq C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) + \frac{b^2}{n} + \frac{2b}{\sqrt{n}} \cdot \sqrt{C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) + \max_{i \in [d]} \Sigma_{ii}} \quad (9)$$

with probability at least $1 - \mathcal{O}(d^{-10})$ for some absolute constant $C > 0$.

Proof. We first recall that each row of B has zero-mean and admits a covariance matrix Σ in Model 1. As every single entry of $B^\top B$ is a summation of sub-Gaussian random variables with parameter σ^2 , then by Bernstein's inequality (see, e.g., Theorem 2.8.1 in [40]) and an argument of union bound, we obtain that

$$\left\| \frac{1}{n} B^\top B - \Sigma \right\|_\infty \leq C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) \quad (10)$$

with probability at least $1 - d^{-10}$ for some absolute constant $C > 0$. By Cauchy Schwartz inequality, we also see that

$$\left\| B^\top M \right\|_\infty \leq \|B\|_{1 \rightarrow 2} \|M\|_{1 \rightarrow 2} \leq b \|B\|_{1 \rightarrow 2}, \quad \left\| M^\top M \right\|_\infty \leq \|M\|_{1 \rightarrow 2}^2 \leq b^2 \quad (11)$$

Then, notice that

$$\frac{1}{n} \|B\|_{1 \rightarrow 2}^2 = \max_{i \in [d]} \left(\frac{1}{n} B^\top B \right)_{ii} \stackrel{(10)}{\leq} C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) + \max_{i \in [d]} \Sigma_{ii} \quad (12)$$

with probability at least $1 - d^{-10}$. Recall that we write

$$A = n\Sigma + (B^\top B - n\Sigma) + (M^\top M + M^\top B + B^\top M) = n\Sigma + E.$$

Combining (10), (11), (12), we see that

$$\frac{1}{n} \|E\|_\infty \leq C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) + \frac{b^2}{n} + \frac{2b}{\sqrt{n}} \cdot \sqrt{C\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \frac{\log d}{n} \right) + \max_{i \in [d]} \Sigma_{ii}}.$$

□

Next, we establish the following lemma, which transforms the upper bound of $\|E\|_\infty/n$ studied in Theorem 18 into a user-friendly bound:

Lemma 19. Define $f := f(C, \Sigma, \sigma, d, n)$ to be the RHS of (9). Assume that $\lambda_1 - \lambda_2 > 0$. There exists an absolute constant $C^* > 0$ such that when

$$n \geq n^* := \max \left\{ C^* \cdot \left[\frac{k^2 \sigma^4 \log d + b^2 k^2 (\sigma^2 + \max \Sigma_{ii})}{(\lambda_1 - \lambda_2)^2 a^4} + \frac{kb^2}{(\lambda_1 - \lambda_2) a^2} \right], \log d \right\},$$

one has $f \leq (\lambda_1 - \lambda_2) \cdot a^2 / (8k)$ with probability at least $1 - d^{-10}$. Moreover, if for $l \geq 1$, $n \geq l \cdot n^*$, then $f \leq (\lambda_1 - \lambda_2) \cdot a^2 / (8\sqrt{l}k)$ with probability at least $1 - d^{-10}$.

Proof. Since $n \geq \log d$, one has $1 \geq \sqrt{\frac{\log d}{n}} \geq \frac{\log d}{n}$. By the fact that $\sqrt{x+y} \leq \sqrt{x} + \sqrt{y}$ for non-negative scalars x, y , it suffices to show that

$$2C\sigma^2 \sqrt{\frac{\log d}{n}} + \frac{b^2}{n} + \frac{2b}{\sqrt{n}} \cdot \left(\sqrt{2C\sigma^2} + \sqrt{\max_{i \in [d]} \Sigma_{ii}} \right) \leq \frac{\lambda_1 - \lambda_2}{8k} \cdot a^2. \quad (13)$$

It is then clear that for some large $C^* > 0$, (13) holds true.

Suppose, in addition, $n \geq l \cdot n^*$, then by definition of f , it is also clear that

$$2C\sigma^2 \sqrt{\frac{\log d}{n}} + \frac{b^2}{n} + \frac{2b}{\sqrt{n}} \cdot \left(\sqrt{2C\sigma^2} + \sqrt{\max_{i \in [d]} \Sigma_{ii}} \right) \leq \frac{\lambda_1 - \lambda_2}{8\sqrt{l}k} \cdot a^2.$$

□

Combining everything we have developed so far, we are ready to prove Theorem 8:

Proof of Theorem 8. Define $f(C, \Sigma, \sigma, d, n)$ to be the RHS of (9). By Theorem 16 and Theorem 18, we obtain that

$$\begin{aligned} \|W^* - vv^\top\|_\infty &\leq \|W^* - vv^\top\|_F \leq \frac{2k}{\lambda_1 - \lambda_2} \cdot \frac{1}{n} \|E\|_\infty + \frac{1}{n} \sqrt{\frac{2k}{\lambda_1 - \lambda_2} \cdot \|E\|_\infty} \\ &\leq \frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2} + \frac{1}{\sqrt{n}} \sqrt{\frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2}} \end{aligned}$$

holds with probability at least $1 - d^{-10}$.

Next, we show that there exists an absolute constant $C^* > 0$ such that when

$$n \geq n^* := \max \left\{ C^* \cdot \left[\frac{k^2 \sigma^4 \log d + b^2 k^2 (\sigma^2 + \max \Sigma_{ii})}{(\lambda_1 - \lambda_2)^2 a^4} + \frac{kb^2}{(\lambda_1 - \lambda_2) a^2} \right], \frac{4}{a^2}, \log d \right\},$$

we have that

$$\frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2} + \frac{1}{\sqrt{n}} \sqrt{\frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2}} \leq \frac{a^2}{2}.$$

Note that the above inequality is implied by the fact that

$$\sqrt{\frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2}} \leq \frac{-\frac{1}{\sqrt{n}} + \sqrt{\frac{1}{n} + 2a^2}}{2} = \frac{a^2}{\sqrt{\frac{1}{n} + 2a^2} + \frac{1}{\sqrt{n}}}.$$

Then it is clear that when $n \geq 4/(a^2)$, one has that $\frac{a^2}{\sqrt{\frac{1}{n} + 2a^2} + \frac{1}{\sqrt{n}}} \geq \frac{a^2}{2a} = \frac{a}{2}$. Therefore, it suffices to show that for some n large enough

$$\sqrt{\frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2}} \leq \frac{a}{2} \iff \frac{2kf(C, \Sigma, \sigma, d, n)}{\lambda_1 - \lambda_2} \leq \frac{a^2}{4} \iff f \leq \frac{\lambda_1 - \lambda_2}{8k} \cdot a^2,$$

which is then implied by Theorem 19. □

Finally, we present the proof of Theorem 9. The high level idea in the proof is to make use of the fact that W^* is close to vv^\top as developed in Theorem 8, and hence there is a simple way to control the quality of the solution we obtained in our algorithm.

Proof of Theorem 9. In the proof, we will constantly use the following fact:

Fact 2. Suppose $x \in \mathbb{R}^d$ is a unit k -sparse vector, then for a $d \times d$ matrix E , one has $|x^\top E x| \leq k \|E\|_\infty$.

Fact 2 can be shown via Holder's inequality and the fact that $\|xx^\top\|_1 = \|x\|_1^2 \leq k \|x\|_2^2 = 1$.

We write $A = n\Sigma + (B^\top B - n\Sigma) + (M^\top M + M^\top B + B^\top M) =: n\Sigma + E$. It is clear that

$$\frac{1}{n} (x^*)^\top A x^* \geq \max_{\substack{\|x\|_2=1 \\ \|x\|_0 \leq k}} x^\top \Sigma x - \max_{\substack{\|x\|_2=1 \\ \|x\|_0 \leq k}} x^\top \left(\frac{1}{n} E \right) x = \lambda_1 - \max_{\substack{\|x\|_2=1 \\ \|x\|_0 \leq k}} x^\top \left(\frac{1}{n} E \right) x \geq \lambda_1 - \frac{k}{n} \|E\|_\infty,$$

where the first inequality uses the basic proposition of max function, and the second inequality follows from Fact 2. Similarly, one can obtain that

$$\frac{1}{n}(x^*)^\top Ax^* \leq \lambda_1 + \frac{k}{n} \|E\|_\infty. \quad (14)$$

We denote \bar{x} the heuristic solution obtained via lines 1 - 2 in Algorithm 2. By the definition of \bar{x} , and the fact that \bar{x} shares the same support with v by Theorem 8 with high probability by Theorem 8, one can see that $\frac{1}{n}\bar{x}^\top A\bar{x} \geq \frac{1}{n}v^\top Av = v^\top \Sigma v + \frac{1}{n}v^\top Ev \geq \lambda_1 - \frac{k}{n} \|E\|_\infty$ where we use Fact 2 in the last inequality. Summing everything up, we see that

$$\frac{(x^*)^\top Ax^* - \bar{x}^\top A\bar{x}}{n} \leq \frac{1}{n}(x^*)^\top Ax^* - \lambda_1 + \frac{k}{n} \|E\|_\infty \leq \frac{1}{n} \text{tr}(AW^*) - \lambda_1 + \frac{k}{n} \|E\|_\infty \leq \frac{2k}{n} \|E\|_\infty. \quad (15)$$

Define $\epsilon := \frac{1}{8\sqrt{l}-1}$. Next, we show that

$$\frac{\lambda_1 - \lambda_2}{8\sqrt{l}k} \cdot a^2 \leq \frac{\lambda_1}{k} \cdot \frac{\epsilon}{2 + \epsilon}. \quad (16)$$

In fact, (16) is equivalent to $2(\lambda_1 - \lambda_2)a^2 \leq \left[8\sqrt{l}\lambda_1 - (\lambda_1 - \lambda_2)a^2\right] \cdot \epsilon$. Since $0 < \lambda_1 - \lambda_2 \leq \lambda_1$, $a \leq 1$, we see that $\frac{2(\lambda_1 - \lambda_2)a^2}{8\sqrt{l}\lambda_1 - (\lambda_1 - \lambda_2)a^2} \leq \frac{2\lambda_1}{8\sqrt{l}\lambda_1 - \lambda_1} = \epsilon$ as desired.

Finally, combining (14), one obtains that with probability at least $1 - d^{-10}$,

$$\frac{2k}{n} \|E\|_\infty \leq \epsilon \left(\lambda_1 - \frac{k}{n} \|E\|_\infty \right) \leq \epsilon \cdot \frac{1}{n} \cdot (x^*)^\top Ax^*, \quad (17)$$

where the first inequality is implied by Theorem 18, Theorem 19, and (16): $\frac{1}{n} \|E\|_\infty \leq \frac{\lambda_1 - \lambda_2}{8\sqrt{l}k} \cdot a^2 \leq \frac{\lambda_1}{k} \cdot \frac{\epsilon}{2 + \epsilon}$. The desired approximation ratio is then given by (15) and (17). \square

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